

# **Frequency domain conditions for the existence of almost periodic solutions in evolutionary variational inequalities**

Volker Reitmann<sup>\*)</sup>

Max-Planck-Institute for  
the Physics of Complex Systems,  
Dresden, Germany

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## 2. Evolutionary variational inequalities

Suppose that  $Y_0$  is a real Hilbert space with  $(\cdot, \cdot)_0$  and  $\|\cdot\|_0$  as scalar product resp. norm. Suppose also that  $A : \mathcal{D}(A) \subset Y_0$  is a closed (unbounded) densely defined linear operator. The Hilbert space  $Y_1$  is defined as  $\mathcal{D}(A)$  equipped with the scalar product

$$(y, \eta)_1 := ((\beta I - A)y, (\beta I - A)\eta)_0, \quad y, \eta \in \mathcal{D}(A), \quad (1)$$

where  $\beta \in \rho(A)$  ( $\rho(A)$  is the resolvent set of  $A$ ) is an arbitrary but fixed number the existence of which we assume.

The Hilbert space  $Y_{-1}$  is by definition the completion of  $Y_0$  with respect to the norm  $\|z\|_{-1} = \|(\beta I - A)^{-1}z\|_0$ . Thus we have the dense and continuous imbedding

$$Y_1 \subset Y_0 \subset Y_{-1} \quad (2)$$

which is called Hilbert space rigging structure. The duality pairing  $(\cdot, \cdot)_{-1,1}$  on  $Y_1 \times Y_{-1}$  is the unique extension by continuity of the functionals  $(\cdot, y)_0$  with  $y \in Y_1$  onto  $Y_{-1}$ .

If  $-\infty \leq T_1 < T_2 \leq +\infty$  are arbitrary numbers, we define the norm for Bochner measurable functions in  $L^2(T_1, T_2; Y_j)$ ,  $j = 1, 0, -1$ , through

$$\|y\|_{2,j} := \left( \int_{T_1}^{T_2} \|y(t)\|_j^2 dt \right)^{1/2}. \quad (3)$$

For an arbitrary interval  $J$  in  $\mathbb{R}$  denote by  $\mathcal{W}(J)$  the space of functions  $y(\cdot) \in L^2_{\text{loc}}(J; Y_1)$  for which  $\dot{y}(\cdot) \in L^2_{\text{loc}}(J; Y_{-1})$  equipped with the norm defined for any compact interval  $[T_1, T_2]$  by

$$\|y(\cdot)\|_{\mathcal{W}(T_1, T_2)} := (\|y(\cdot)\|_{2,1}^2 + \|\dot{y}(\cdot)\|_{2,-1}^2)^{1/2}. \quad (4)$$

By an imbedding theorem we can assume that any function from  $\mathcal{W}(J)$  belongs to  $C(J; Y_0)$ . Assume now that  $\Xi$  is an other real Hilbert space with scalar product  $(\cdot, \cdot)_{\Xi}$  and norm  $\|\cdot\|_{\Xi}$ , respectively, and  $J \subset \mathbb{R}$  is an arbitrary interval.

Introduce (with  $A$  from above) the linear continuous operators

$$A : Y_1 \rightarrow Y_{-1} \quad \text{and} \quad B : \Xi \rightarrow Y_{-1} \quad (5)$$

and the maps

$$\varphi : J \times Y_1 \rightarrow \Xi, \quad (6)$$

$$\psi : Y_1 \rightarrow \mathbb{R}_+, \quad (7)$$

and  $f : J \rightarrow Y_{-1}. \quad (8)$

Note that in many applications  $\varphi$  is a material law nonlinearity,  $B$  is a control operator,  $\psi$  is a contact-type or friction-type functional, and  $f$  is a perturbation. Consider for a.a.  $t \in J$  the evolutionary variational inequality

$$\begin{aligned} (\dot{y}(t) - Ay(t) - B\varphi(t, y(t)) - f(t), \eta - y(t))_{-1,1} \\ + \psi(\eta) - \psi(y(t)) \geq 0, \quad \forall \eta \in Y_1. \end{aligned} \quad (9)$$

For any  $f \in L^2_{\text{loc}}(J; Y_{-1})$  a function  $y(\cdot) \in \mathcal{W}(J) \cap C(J; Y_0)$  is said to be a solution of (9) if this inequality is satisfied for all test functions  $\eta \in Y_1$ .

In addition, we make the following assumptions.

**(A1)** For any  $t \in J$  the map  $\mathcal{A}(t)y := -Ay - B\varphi(t, y) : Y_1 \rightarrow Y_{-1}$  is semicontinuous, i.e., for any  $t \in J$  and any  $y, \eta, z \in Y_1$  the  $\mathbb{R}$ -valued function  $\tau \mapsto (\mathcal{A}(t)(y - \tau\eta), z)_{-1,1}$  is continuous.

**(A2)** For any  $\eta \in Y_1$  and any bounded set  $S \subset Y_1$  the family of functions  $\{(B\varphi(\cdot, y), \eta)_{-1,1}, y \in S\}$  is equicontinuous on any compact subinterval of  $J$ .

**(A3)**  $\varphi(\cdot, 0) \equiv 0$  on  $J$  and there exist operators  $N \in \mathcal{L}(Y_1, \Xi)$  and  $M = M^* \in \mathcal{L}(\Xi, \Xi)$  such that

$$\begin{aligned} & (\varphi(t, y_1) - \varphi(t, y_2), N(y_1 - y_2))_{\Xi} \\ & \geq (\varphi(t, y_1) - \varphi(t, y_2), M(\varphi(t, y_1) - \varphi(t, y_2)))_{\Xi}, \\ & \forall t \in J, \forall y_1, y_2 \in Y_1. \end{aligned} \quad (10)$$

**(A4)** There exists a quadratic form  $\mathcal{G}$  on  $Y_0 \times \Xi$  and a continuous functional  $\Phi : Y_0 \rightarrow \mathbb{R}_+$  such that for any  $y_1(\cdot), y_2(\cdot) \in L^2_{\text{loc}}(J; Y_0)$  and a.a.  $s, t \in J, s < t$ , we have

$$\begin{aligned} \int_s^t \mathcal{G}(y_1(\tau) - y_2(\tau), \varphi(\tau, y_1(\tau)) - \varphi(\tau, y_2(\tau))) d\tau \\ \geq \frac{1}{2} \Phi(y_1(\tau) - y_2(\tau))|_s^t. \end{aligned} \quad (11)$$

Furthermore, there are two constants  $0 < \rho_1 < \rho_2$  such that

$$\rho_1 \|y\|_0^2 \leq \Phi(y) \leq \rho_2 \|y\|_0^2, \quad \forall y \in Y_0. \quad (12)$$

In addition to **(A1) – (A4)** we suppose that there exists a number  $\lambda > 0$  such that the following assumptions are satisfied:

**(A5)** For any  $T > 0$  and any  $f \in L^2(0, T; Y_{-1})$  the problem  $\dot{y} = (A + \lambda I)y + f(t), y(0) = y_0$ , is well-posed, i.e., for arbitrary  $y_0 \in Y_0, f(\cdot) \in L^2(0, T; Y_{-1})$  there exists a unique solution  $y(\cdot) \in \mathcal{W}(0, T)$  with  $\dot{y}(\cdot) \in L^2(0, T; Y_{-1})$  satisfying the equation in a variational sense and depending continuously on the initial data, i.e.,

$$\|y(\cdot)\|_{\mathcal{W}(0, T)}^2 \leq c_1 \|y_0\|_0^2 + c_2 \|f(\cdot)\|_{2, -1}^2, \quad (13)$$

where  $c_1 > 0$  and  $c_2 > 0$  are some constants. Furthermore it is supposed that any solution of  $\dot{y} = (A + \lambda I)y, y(0) = y_0$ , is exponentially decreasing for  $t \rightarrow +\infty$ , i.e., there exist constants  $c_3 > 0$  and  $\varepsilon > 0$  such that

$$\|y(t)\|_0 \leq c_3 e^{-\varepsilon t} \|y_0\|_0, \quad t > 0. \quad (14)$$

**(A6)** The operator  $A + \lambda I \in \mathcal{L}(Y_1, Y_{-1})$  is regular, i.e., for any  $T > 0, y_0 \in Y_1, z_T \in Y_1$  and  $f \in L^2(0, T; Y_0)$  the solution of the direct problem

$$\dot{y} = (A + \lambda I)y + f(t), \quad y(0) = y_0$$

and of the dual problem

$$\dot{z} = -(A + \lambda I)^* z + f(t), \quad z(0) = z_T$$

are strongly continuous in  $t$  in the norm of  $Y_1$ .

**(A7)** The pair  $(A + \lambda I, B)$  is  $L^2$ -controllable, i.e., for arbitrary  $y_0 \in Y_0$  there exists a control  $\xi(\cdot) \in L^2(0, +\infty; \Xi)$  such that the problem  $\dot{y} = (A + \lambda I)y + B\xi, y(0) = y_0$ , is well-posed in the variational sense on  $(0, +\infty)$ .

**(A8)** Let denote by  $H^c$  and  $L^c$  the complexification of a linear space  $H$  and a linear operator  $L$ , respectively, by  $\chi(s) = (sI^c - A^c)^{-1}B^c, s \notin \rho(A^c)$ , the transfer operator, and by  $\mathcal{G}^c$  the Hermitian extension of  $\mathcal{G}$ .

There exist a number  $\Theta > 0$  such that with  $\rho_2$  from (12) and the imbedding constants  $\gamma$  from  $Y_1 \subset Y_0$

$$\begin{aligned} & \Theta [\operatorname{Re}(\xi, N^c \chi(i\omega - \lambda) \xi)_{\Xi^c} + (\xi, M^c \xi)_{\Xi^c}] \\ & + \mathcal{G}^c(\chi(i\omega - \lambda) \xi, \xi) + \gamma \lambda \rho_2 \|\chi(i\omega - \lambda) \xi\|_{Y_1^c}^2 < 0, \\ & \forall \omega \in \mathbb{R}, \forall \xi \in \Xi^c. \end{aligned} \quad (15)$$

**(A9)** For any positive  $P = P^* \in \mathcal{L}(Y_0, Y_0)$  and  $\delta > 0$  which are with  $\gamma, \rho_2$  and  $\Theta > 0$  from **(A8)** solution of the inequality

$$\begin{aligned} & ((A + \lambda I)y + B\xi, Py)_{-1,1} + \Theta [(\xi, Ny)_{\Xi} - (\xi, M\xi)_{\Xi}] \\ & + \mathcal{G}(y, \xi) + \gamma \lambda \rho_2 \|y\|_1^2 \leq -\delta [\|y\|_1^2 + \|\xi\|_{\Xi}^2] \\ & \forall \xi \in \Xi, \forall y \in Y_1, \end{aligned} \quad (16)$$

we have

$$\begin{aligned} \psi(y_1) - \psi(y_1 - P(y_1 - y_2)) + \psi(y_2) - \psi(y_2 + P(y_1 - y_2)) & \geq 0 \\ \forall y_1, y_2 \in Y_1, \end{aligned} \quad (17)$$

and on  $Y_1$  the function  $\psi_P(y) := \psi(y - Py) - \psi(y)$  is convex and lower continuous, i.e.,  $y_k \rightarrow y$  in  $Y_1$  implies

$$\psi_P(y) \leq \liminf_{k \rightarrow \infty} \psi_P(y_k).$$

**(A10)** For any  $y_0 \in Y_0$  the existence of at least one solution  $y(\cdot)$  of (9) on  $\mathbb{R}_+$  with  $y(0) = y_0$  is supposed. The uniqueness to the right and the continuous dependence of solutions on initial states is assumed in the following sense:

a) If  $y_1, y_2$  are two solutions of (9) on  $\mathbb{R}_+$  and  $y_1(t_0) = y_2(t_0)$  for some  $t_0 \geq 0$  then  $y_1(t) = y_2(t)$ ,  $\forall t \geq t_0$ .

b) If  $y(\cdot, a_k)$ ,  $k = 1, 2, \dots$ , are solutions of (9) with  $y(t_0, a_k) = a_k$  on  $J_0 = [t_0, t_1]$  or  $J_0 = [t_1, t_0]$  and  $a_k \rightarrow a$  for  $k \rightarrow \infty$  in  $Y_0$  then there exists a subsequence  $k_n \rightarrow \infty$  with  $y(\cdot, a_{k_n}) \rightarrow y$  for  $n \rightarrow \infty$  in  $C(J_0; Y_0)$  and  $y$  is a solution of (9) on  $J_0$  with  $y(t_0) = a$ .

### 3 Existence of bounded solutions

Let  $(E, \|\cdot\|_E)$  be a Banach space. Denote by  $C_b(\mathbb{R}; E) \subset C(\mathbb{R}; E)$  the subspace of bounded continuous functions equipped with the norm  $\|f\|_{C_b} = \sup_{t \in \mathbb{R}} \|f(t)\|_E$ , which gives a Banach space structure.

The space  $BS^2(\mathbb{R}; E)$  of *bounded* (with exponent 2) *in the sense of Stepanov functions* is the subspace of all functions  $f$  from  $L^2_{loc}(\mathbb{R}; E)$  which have a finite norm

$$\|f\|_{S^2}^2 = \sup_{t \in \mathbb{R}} \int_t^{t+1} \|f(\tau)\|_E^2 d\tau .$$

**Lemma 3.1** Assume that the assumptions **(A3)** – **(A10)** are satisfied. Then there exists a positive operator  $P = P^* \in \mathcal{L}(Y_0, Y_0)$  such that  $P \in \mathcal{L}(Y_{-1}, Y_0) \cap \mathcal{L}(Y_0, Y_1)$  and the functional

$$V(y) := \frac{1}{2}(y, Py)_0 + \frac{1}{2} \Phi(y) , \quad y \in Y_0 ,$$

has the following properties:

a) Suppose that  $y(\cdot)$  is an arbitrary solution of (9). Then for any  $s, t \in J, s \leq t$ , we have

$$V(y(t))|_s^t + 2\lambda \int_s^t V(y(\tau)) d\tau \leq \int_s^t (f(\tau), Py(\tau))_{-1,1} d\tau. \quad (1)$$

b) Suppose that  $f \in BS^2(\mathbb{R}_+; Y_{-1})$ . Then there exist constants  $\alpha > 0$  and  $\beta > 0$  such that for any solution  $y(\cdot)$  of (9) and any time interval  $[s, t] \subset \mathbb{R}_+$  from  $\|y(\tau)\|_0 \geq \beta$  on  $[s, t]$  it follows that

$$V(y(\tau))|_s^t \leq -\alpha \int_s^t \|y(\tau)\|_0^2 d\tau. \quad (2)$$

c) Let  $y_1(\cdot), y_2(\cdot)$  be solutions of (9) with  $f = f_i \in L_{loc}^2(J; Y_{-1})$ ,  $i = 1, 2$ . Then for any  $s, t \in J, s \leq t$ , we have

$$\begin{aligned} & V(y_1(\tau) - y_2(\tau))|_s^t + 2\lambda \int_s^t V(y_1(\tau) - y_2(\tau)) d\tau \\ & \leq \int_s^t (f_1(\tau) - f_2(\tau), P(y_1(\tau) - y_2(\tau)))_{-1,1} d\tau. \end{aligned} \quad (3)$$

d) Suppose that  $y_1(\cdot), y_2(\cdot)$  are two solutions of (9) Then for any  $t_0 \in J$  and all  $t \geq t_0$  ( $t \leq t_0$ , respectively),  $t \in J$ , we have

$$\begin{aligned} V(y_1(t) - y_2(t)) & \leq e^{-2\lambda(t-t_0)} V(y_1(t_0) - y_2(t_0)). \\ & (\geq) \end{aligned} \quad (4)$$

**Proof** Due to the assumptions **(A5) – (A9)** from the Likhtarnikov-Yakubovich frequency-theorem (Likhtarnikov, Yakubovich; 1976) it

follows that there exists an operator  $P = P^* \in \mathcal{L}(Y_0, Y_0)$  such that  $P \in \mathcal{L}(Y_{-1}, Y_0) \cap \mathcal{L}(Y_0, Y_1)$  and a number  $\delta > 0$  such that

$$\begin{aligned} & ((A + \lambda I)y + B\xi, Py)_{-1,1} + \Theta [(\xi, Ny)_{\Xi} - (\xi, M\xi)_{\Xi}] \\ & + \mathcal{G}(y, \xi) + \gamma\lambda\rho_2\|y\|_1^2 \leq -\delta [\|y\|_1^2 + \|\xi\|_{\Xi}^2] \\ & \quad \forall y \in Y_1, \quad \forall \xi \in \Xi. \end{aligned} \quad (5)$$

If we put in (5)  $\xi = 0$  we get the inequality

$$((A + \lambda I)y, Py)_{-1,1} \leq -\delta\|y\|_1^2, \quad \forall y \in Y_1. \quad (6)$$

Using the assumption **(A5)** it follows from (6) that  $P > 0$ . Note that  $P$  is not necessarily coercive. In order to get this property we consider the functional

$$V(y) := \frac{1}{2}(y, Py)_0 + \frac{1}{2}\Phi(y), \quad \forall y \in Y_0. \quad (7)$$

Due to the property  $P > 0$  and the assumption **(A4)**  $V$  is coercive.

Let us prove the assertion a). With the given solution  $y(\cdot)$  of (9) we consider for any  $t \in J$  the test function  $\eta = -Py(t) + y(t) \in Y_1$ . It follows from (9) that

$$\begin{aligned} & (\dot{y}(t), Py(t))_{-1,1} + \lambda(y(t), Py(t))_0 \\ & - ((A + \lambda I)y(t) + B\varphi(t, y(t), Py(t)))_{-1,1} + \psi(y(t)) \\ & - \psi(y(t) - Py(t)) \leq (f(t), Py(t))_{-1,1}. \end{aligned} \quad (8)$$

Using the estimate (5) we derive from (8) the inequality

$$\begin{aligned} & (\dot{y}(t), Py(t))_{-1,1} + \lambda(y(t), Py(t))_0 + \Theta [(\varphi(t, y(t)), Ny(t))_{\Xi} \\ & - (\varphi(t, y(t)), M\varphi(t, y(t)))_{\Xi}] + \mathcal{G}(y(t), \varphi(t, y(t))) \\ & + \gamma\lambda\rho_2\|y(t)\|_1^2 + \delta [\|y(t)\|_1^2 + \|\varphi(t, y(t))\|_{\Xi}^2] \\ & + \psi(y(t)) - \psi(y(t) - Py(t)) \leq (f(t), Py(t))_{-1,1}. \end{aligned} \quad (9)$$

Along the solution  $y(\cdot)$  we have by **(A3)** and **(A9)**

$$\begin{aligned} & \Theta [(\varphi(t, y(t)), Ny(t))_{\Xi} - (\varphi(t, y(t)), M\varphi(t, y(t)))_{\Xi}] \geq 0, \\ & \psi(y(t)) - \psi(y(t) - Py(t)) \geq 0, \delta [\|y(t)\|_1^2 + \|\varphi(t, y(t))\|_{\Xi}^2] \geq 0. \end{aligned} \quad (10)$$

Integrating (9) on a time interval  $[s, t]$ ,  $s, t \in J$ , we get

$$\begin{aligned} & \frac{1}{2} (y(\tau), Py(\tau))_0 \Big|_s^t + \lambda \int_s^t (y(\tau), Py(\tau))_0 d\tau \\ & + \int_s^t \mathcal{G}(y(\tau), \varphi(\tau, y(\tau))) d\tau + \gamma\lambda\rho_2 \int_s^t \|y(\tau)\|_1^2 d\tau \\ & \leq \int_s^t (f(\tau), Py(\tau))_{-1,1} d\tau. \end{aligned} \quad (11)$$

From **(A4)** it follows that

$$\begin{aligned} & \int_s^t \mathcal{G}(y(\tau), \varphi(\tau, y(\tau))) + \gamma\lambda\rho_2 \int_s^t \|y(\tau)\|_1^2 d\tau \\ & \geq \frac{1}{2} \Phi(y(\tau)) \Big|_s^t + \lambda \int_s^t \Phi(y(\tau)) d\tau. \end{aligned} \quad (12)$$

Taking into account now (11) and (12) we obtain that

$$\begin{aligned} & \left[ \frac{1}{2} (y(\tau), Py(\tau))_0 + \frac{1}{2} \Phi(y(\tau)) \right] \Big|_s^t \\ & + 2\lambda \int_s^t \left[ \frac{1}{2} (y(\tau), Py(\tau))_0 + \frac{1}{2} \Phi(y(\tau)) \right] d\tau \\ & \leq \int_s^t (f(\tau), Py(\tau))_{-1,1} d\tau. \end{aligned} \quad (13)$$

From (13) we conclude that (1) is satisfied.

Now let us prove d). With respect to the solution  $y_1$  we consider the test function  $\eta = y_1 + P(y_2 - y_1)$  in order to derive from (9) the inequality (we suppress  $t$  in  $y_i$ )

$$\begin{aligned} & (\dot{y}_1 - Ay_1 - B\varphi(t, y_1) - f(t), P(y_2 - y_1))_{-1,1} \\ & + \psi(y_1 + P(y_2 - y_1)) - \psi(y_1) \geq 0. \end{aligned} \quad (14)$$

With respect to the solution  $y_2$  we consider the test function  $\eta = y_2 - P(y_2 - y_1)$ . This gives

$$\begin{aligned} & (\dot{y}_2 - Ay_2 - B\varphi(t, y_2) - f(t), -P(y_2 - y_1))_{-1,1} \\ & + \psi(y_2 - P(y_2 - y_1)) - \psi(y_2) \geq 0. \end{aligned} \quad (15)$$

If we add the inequalities (14) and (15) we receive

$$\begin{aligned}
& (\dot{y}_1 - \dot{y}_2, P(y_2 - y_1))_{-1,1} + (A(y_2 - y_1) + B[\varphi(t, y_2) - \varphi(t, y_1)] , \\
& P(y_2 - y_1))_{-1,1} + \psi(y_1 + P(y_2 - y_1)) - \psi(y_1) \\
& + \psi(y_2 - P(y_2 - y_1)) - \psi(y_2) \geq 0
\end{aligned} \tag{16}$$

or, equivalently,

$$\begin{aligned}
& (\dot{y}_2 - \dot{y}_1, P(y_2 - y_1))_{-1,1} - (A(y_2 - y_1) + B[\varphi(t, y_2) - \varphi(t, y_1)] , \\
& P(y_2 - y_1))_{-1,1} + \psi(y_1) - \psi(y_1 + P(y_2 - y_1)) \\
& + \psi(y_2) - \psi(y_2 - P(y_2 - y_1)) \leq 0 .
\end{aligned} \tag{17}$$

From (17) and **(A9)** it follows that

$$\begin{aligned}
& (\dot{y}_2 - \dot{y}_1, P(y_2 - y_1))_{-1,1} - (A(y_2 - y_1) \\
& + B[\varphi(t, y_2) - \varphi(t, y_1)] , P(y_2 - y_1))_{-1,1} \leq 0 .
\end{aligned} \tag{18}$$

and, consequently,

$$\begin{aligned}
& (\dot{y}_2 - \dot{y}_1, P(y_2 - y_1))_{-1,1} + \lambda(y_2 - y_1, P(y_2 - y_1))_0 \\
& - ((A + \lambda I)(y_2 - y_1) + B[\varphi(t, y_2) - \varphi(t, y_1)] , \\
& P(y_2 - y_1))_{-1,1} \leq 0 .
\end{aligned} \tag{19}$$

We use again use the inequality (5) with  $y = y_2 - y_1$  and  $\xi = \varphi(t, y_2) - \varphi(t, y_1)$  to derive from (19) the estimate

$$\begin{aligned}
& (\dot{y}_2 - \dot{y}_1, P(y_2 - y_1))_{-1,1} + \lambda(y_2 - y_1, P(y_2 - y_1))_0 \\
& + \Theta[(\varphi(t, y_2) - \varphi(t, y_1), N(y_2 - y_1))_{\Xi} - (\varphi(t, y_2) - \varphi(t, y_1), \\
& M(\varphi(t, y_2) - \varphi(t, y_1))_{\Xi})] + \mathcal{G}(y_2 - y_1, \varphi(t, y_2) - \varphi(t, y_1)) \\
& + \gamma\rho_2\lambda\|y_2 - y_1\|_1^2 + \delta[\|y_2 - y_1\|_1^2 + \|\varphi(t, y_2) - \varphi(t, y_1)\|_{\Xi}^2] \leq 0 .
\end{aligned} \tag{20}$$

Along the solution pair  $y_1, y_2$  we have according to **(A3)** the property

$$\begin{aligned}
& \Theta[(\varphi(t, y_2) - \varphi(t, y_1), N(y_2 - y_1))_{\Xi} \\
& - (\varphi(t, y_2) - \varphi(t, y_1), M(\varphi(t, y_2) - \varphi(t, y_1))_{\Xi})] \geq 0 .
\end{aligned} \tag{21}$$

Integration of (20) on  $[s, t] \subset J$  under consideration of (21) and  $\delta > 0$  gives

$$\begin{aligned} & \frac{1}{2} (y_2 - y_1, P(y_2 - y_1))_0 \Big|_s^t + \lambda \int_s^t (y_2 - y_1, P(y_2 - y_1))_0 d\tau \\ & \quad + \int_s^t \mathcal{G}(y_2 - y_1, \varphi(\tau, y_2) \\ & \quad - \varphi(\tau, y_1)) d\tau + \gamma \rho_2 \lambda \int_s^t \|y_2 - y_1\|_1^2 d\tau \leq 0. \end{aligned} \quad (22)$$

From **(A4)** it follows that

$$\begin{aligned} & \int_s^t \mathcal{G}(y_2 - y_1, \varphi(\tau, y_2) - \varphi(\tau, y_1)) d\tau + \gamma \rho_2 \lambda \int_s^t \|y_2 - y_1\|_1^2 d\tau \\ & \geq \frac{1}{2} \Phi(y_2 - y_1) \Big|_s^t + \lambda \int_s^t \Phi(y_2 - y_1) d\tau. \end{aligned} \quad (23)$$

Using (23) we derive from (22) the inequality

$$\begin{aligned} & \frac{1}{2} [(y_2 - y_1, P(y_2 - y_1))_0 + \Phi(y_2 - y_1)] \Big|_s^t \\ & + 2\lambda \int_s^t \left[ \frac{1}{2} (y_2 - y_1, P(y_2 - y_1))_0 + \frac{1}{2} \Phi(y_2 - y_1) \right] d\tau \leq 0. \end{aligned} \quad (24)$$

From (24) we conclude that the function

$$m(t) := \frac{1}{2} [(y_2(t) - y_1(t), P(y_2(t) - y_1(t)))_0 + \Phi(y_2(t) - y_1(t))]$$

satisfies the inequality

$$m(\tau) \Big|_s^t + 2\lambda \int_s^t m(\tau) d\tau \leq 0,$$

from which (1) follows immediately.

**Lemma 3.2** Suppose that  $V : Y_0 \rightarrow \mathbb{R}_+$  is a continuous function which satisfies the following properties.

a) There exist constants  $0 < \gamma_1 < \gamma_2$  with

$$\gamma_1 \|y\|_0^2 \leq V(y) \leq \gamma_2 \|y\|_0^2, \quad \forall y \in Y_0. \quad (25)$$

b) There exist constants  $\alpha > 0$  and  $\beta > 0$  such that for any solution  $y(\cdot)$  of (9) and any time interval  $[s, t] \subset \mathbb{R}_+$  from  $\|y(\tau)\|_0 \geq \beta$  on  $[s, t]$  it follows that

$$V(y(\tau))|_s^t \leq -\alpha \int_s^t \|y(\tau)\|_0^2 d\tau. \quad (26)$$

If  $\eta > 0$  is an arbitrary number satisfying the inclusion

$$S := \{y \in Y_0 : V(y) \leq \eta\} \supset \{y \in Y_0 : \|y\|_0 \leq \beta\}, \quad (27)$$

then  $S$  is positively invariant for (9) and any solution of (9) enters  $S$  in a certain finite time.

**Proof** a) Suppose that  $y(\cdot)$  is a solution of (9) with  $y(t_0) \in S$  and  $y(t_1) \notin S$  for some  $t_1 > t_0$ . It follows that  $V(y(t_1)) > \eta$  and  $\|y(t_1)\|_0 > \beta$ . Denote by  $t'$  the maximal time in  $(t_0, t_1)$  with  $\|y(t')\|_0 = \beta$ . On the interval  $(t', t_1)$  the inequality  $\|y(\tau)\|_0 > \beta$  is satisfied. It follows by (26) that

$$V(y(\tau))|_{t'}^{t_1} \leq -\alpha \int_{t'}^{t_1} \|y(\tau)\|_0^2 d\tau < 0, \quad (28)$$

and, consequently,  $V(y(t_1)) < V(y(t')) \leq \eta$ . But this is a contradiction which shows that  $y(t_1) \in S$ .

b) Consider a solution  $y(\cdot)$  of (9) with  $y(t_0) \notin S$  and  $\|y(t_0)\|_0 > \beta$ . Assume that  $y(t) \notin S, \forall t \geq t_0$ , i.e.,

$$V(y(t)) > \eta \quad \text{and} \quad \|y(t)\|_0 > \beta, \quad \forall t \geq t_0. \quad (29)$$

From (28) and (29) it follows that for all  $t \geq t_0$

$$V(y(\tau))|_{t_0}^t \leq -\alpha \int_{t_0}^t \|y(\tau)\|_0^2 d\tau \leq -\alpha \beta(t - t_0)$$

and

$$0 < \eta < V(y(t)) \leq V(y(t_0)) - \alpha \beta(t - t_0).$$

But the last inequality is impossible for large  $t$ .

**Corollary 3.1** Suppose that the assumptions **(A3)** – **(A10)** are satisfied and

$$f \in BS^2(\mathbb{R}_+; Y_{-1}) . \quad (30)$$

Then any solution  $y(\cdot)$  of (9) belongs to  $C_b(\mathbb{R}_+; Y_0)$ .

**Proof** From the assumptions **(A3)** – **(A10)** it follows that there exists a continuous function  $V$  which satisfies (1). Together with Lemma 3.1 we get the boundedness of any solution in  $Y_0$  on  $\mathbb{R}_+$ .

(Pankov; 1986, Yakubovich; 1964)

**Lemma 3.3** Suppose that there exists a bounded and closed set  $S \subset Y_0$  which has the following properties:

a) If for a solution  $y(\cdot)$  of (9) we have  $y(t_0) \in S$  then  $y(t) \in S, \forall t \geq t_0$ ;

b) Any solution  $y(\cdot)$  of (9) enters the set  $S$  at a certain time.

Then the inequality (9) has a solution  $y \in C_b(\mathbb{R}; Y_0)$  such that  $y(t) \in S, \forall t \in \mathbb{R}$

**Proof** Recall that  $y(\cdot, a)$  denotes a solution of (9) with  $y(0, a) = a$ . Put  $S_0 := S$  and define for  $j = 1, 2, \dots$  the sets

$$S_j := \{a \in Y_0 : y(-j, a) \in S_0\} .$$

It is clear that

$$S_0 \supset S_1 \supset S_2 \supset \dots . \quad (31)$$

Let us show that any set  $S_j$  is closed. Suppose for this that  $\{a_k\}$  is a sequence of points in  $S_j$  with  $a_k \rightarrow a$  in  $Y_0$ . By assumption there exists a subsequence  $k_m \rightarrow \infty$  and a solution  $y(\cdot, a)$  of (9) such that  $y(-j, a_{k_m}) \rightarrow y(-j, a)$  in  $Y_0$ . Since  $S_0$  is closed it follows that  $y(-j, a) \in S_0$ , i.e.,  $a \in S_j$ .

From (31) and the closedness of  $S_j$  it follows that there exists a point  $a_0 \in \cap S_j$ . For any solution  $y(\cdot, a_0)$  of (9) we have  $y(t, a_0) \in S_0, t \geq 0$ . From  $a_0 \in S_j, j = 1, 2, \dots$ , it follows that there exists a solution  $y_j(\cdot, a_0)$  with  $y_j(-j, a_0) \in S_0, y_j(0, a_0) = a_0$ , and  $y_j(t, a_0) \in S_0, \forall t \geq -j$ . Choose a subsequence  $\{j_m\}$  with  $y_{j_m}(-1, a_0) \rightarrow a_1$ . By assumption we can assume that there exists a solution  $y^{(1)}(\cdot)$  of (9) with  $y_{j_m}(\cdot, a_0) \rightarrow y^{(1)}(\cdot)$  on  $[-1, 0]$ . In addition to this we have  $y^{(1)}(0) = a_0$  and  $y^{(1)}(-1) = a_1 \in S_0$ . Take now a subsequence  $\{j_{m_l}\}$  with  $y_{j_{m_l}}(-2, a_0) \rightarrow a_2 \in S_0$  for  $l \rightarrow \infty$ . Again there is a solution  $y^{(2)}(\cdot)$  of (9) such that  $y_{j_{m_l}}(\cdot, a_0) \rightarrow y^{(2)}(\cdot)$  on  $[-2, -1], y^{(2)}(-2) = a_2 \in S_2$ , and  $y^{(2)}(-1) = a_1$ . If we continue this process we get on any interval  $[-m, -m + 1]$  a solution  $y^{(m)}(\cdot)$  satisfying  $y^{(m)}(-m) = a_m \in S_0$  and  $y^{(m)}(-m + 1) = a_{m-1} \in S_0, m = 1, 2, \dots$ . The bounded on  $\mathbb{R}$  solution of (9) is defined by  $y(t) = y^{(m)}(t), t \in [-m, -m + 1]$ .

#### 4 Existence of almost periodic solutions

Let  $(E, \|\cdot\|_E)$  be a Banach space and let  $f : \mathbb{R} \rightarrow E$  be continuous. If  $\varepsilon > 0$ , then a number  $T \in \mathbb{R}$  is called  $\varepsilon$ -almost period of  $f$  if  $\sup_{t \in \mathbb{R}} \|f(t + T) - f(t)\|_E \leq \varepsilon$ . The function  $f$  is called *Bohr almost periodic* or *uniformly almost periodic* (shortly  $f \in \text{CAP}(\mathbb{R}; E)$  or uniformly a.p.) if for each  $\varepsilon > 0$  there is  $R > 0$  such that each interval  $(r, r + R) \subset \mathbb{R} (r \in \mathbb{R})$  contains at least one  $\varepsilon$ -almost period of  $f$ . For a function  $f \in L^2_{\text{loc}}(\mathbb{R}; E)$  define the *Bochner transform*  $f^b$  by

$$f^b(t) := f(t + \eta), \eta \in [0, 1], t \in \mathbb{R},$$

as a (continuous) function with values in  $L^2(0, 1; E)$ . A function  $f \in BS^2(\mathbb{R}; E)$  is called an *almost periodic function in the sense of Stepanov* (shortly  $S^2$ -a.p.) if  $f^b \in \text{CAP}(\mathbb{R}; L^2(0, 1; E))$ . The  $\varepsilon$ -almost periods of the function  $f^b$  are called the  $\varepsilon$ -almost periods of  $f$ . The space of  $S^2$ -a.p. functions with values in  $E$  is denoted by  $S^2(\mathbb{R}; E)$ . Obviously,  $\text{CAP}(\mathbb{R}; E) \subset S^2(\mathbb{R}; E)$ .

In order to derive sufficient conditions for the existence of almost periodic solutions in (9) we need one additional assumption.

**(A11)** The family of functions  $\{\varphi(\cdot, y), y \in Y_1\}$  is uniformly almost periodic on any set  $\{y \in Y_1 : \|y\|_1 \leq \text{const}\}$ .

**Theorem 4.1** Under the assumptions **(A3)** – **(A11)** there exists for any  $f \in BS^2(\mathbb{R}; Y_{-1})$  a unique bounded on  $\mathbb{R}$  solution  $y_*(\cdot)$  of (9). This solution is exponentially stable in the whole, i.e., there exist positive constants  $c > 0$  and  $\varepsilon > 0$  such that for any other solution  $y$  of (9), any  $t_0 \in \mathbb{R}$  and any  $t \geq t_0$  we have

$$\|y(t) - y_*(t)\|_0 \leq c e^{-\varepsilon(t-t_0)} \|y(t_0) - y_*(t_0)\|_0. \quad (1)$$

If  $\varphi$  satisfies **(A11)** and  $f \in S^2(\mathbb{R}; Y_{-1})$  then  $y_*(\cdot)$  belongs to CAP  $(\mathbb{R}; Y_0)$ .

**Proof** (For the case  $\varphi(t, y) \equiv \varphi(y)$ ) Under our assumptions and for  $f \in BS^2(\mathbb{R}; Y_{-1})$  the existence of a bounded on  $\mathbb{R}$  solution  $y_*(\cdot)$  of (9) follows from Lemma 3.3. The exponential stability of  $y_*(\cdot)$  results from (4). The inequality (4) implies immediately that  $y_*(\cdot)$  is the only bounded on  $\mathbb{R}$  solution. Suppose  $f \in S^2(\mathbb{R}; Y_{-1})$  and consider an arbitrary  $\varepsilon$ -almost period of  $f$ . Define the function  $w(t) := y_*(t + T) - y_*(t)$ . Using Lemma 3.1 it is easy to show that there are constants  $c_1 > 0$  and  $c_2 > 0$  such that for all  $t_0 \in \mathbb{R}$  and arbitrary  $t \geq t_0$

$$V^{1/2}(w(t)) \leq c_1 e^{-(t-t_0)} V^{1/2}(w(t_0)) + c_2 \varepsilon. \quad (2)$$

If we choose  $t_0 \rightarrow -\infty$  for any fixed  $t$  we get the inequality

$$V^{1/2}(w(t)) \leq c_2 \varepsilon,$$

which shows that  $T$  is an  $c_2 \varepsilon$ -almost period with respect to the metric  $V^{1/2}$ .

### Example 4.1

$$\begin{aligned} Y_0 &= L^2(0, 1), & Y_1 &= W^{1,2}(0, 1) \\ (u, v)_1 &= \int_0^1 (uv + u_x v_x) dx \end{aligned} \quad (3)$$

$$A : Y_1 \rightarrow Y_{-1}, (Au, v)_{-1,1} = \int_0^1 (Au)(x)v(x)dx := - \int_0^1 (au_x v_x + buv) dx, \forall u, v \in W^{1,2}(0,1) \quad (4)$$

$$\begin{aligned} & (" Au = au - bu_x ") \\ \Xi &= \mathbb{R}, B : \Xi \rightarrow Y_{-1}, \\ (B\xi, v)_{-1,1} &:= a\xi v(1), \quad \forall \xi \in \mathbb{R}, \forall v \in W^{1,2}(0,1) \end{aligned} \quad (5)$$

$$\begin{aligned} & (" B = a\delta(x-1) ") \\ u_x(0, t) &= 0, \quad u_x(1, t) = g(w(t)) + f(t), \end{aligned} \quad (6)$$

$g : \mathbb{R} \rightarrow \mathbb{R}$  continuous,  $f \in L^2_{loc}(\mathbb{R}) \cap \mathbf{CAP}(\mathbb{R})$

$\psi : W^{1,2}(0,1) \rightarrow \mathbb{R}$

$K : Y_1 \rightarrow \mathbb{R}$  linear continuous,  $K(u) = \int_0^1 k(x)u(x,t) dx,$

$\varphi : L^2(0,1) \rightarrow \mathbb{R}$  given by

$$u \in L^2(0,1) \mapsto w(\cdot) = K(u(\cdot)) \mapsto g(w(\cdot)) \in \mathbb{R} \quad (7)$$

$$\begin{aligned} \exists \mu_0 > 0 \quad \forall w_1, w_2 : 0 \leq (g(w_1) - g(w_2))(w_1 - w_2) \\ \leq \mu_0 (w_1 - w_2)^2, \end{aligned} \quad (8)$$

$\exists c_1 > 0 \quad \forall w_1, w_2 \in \mathcal{W}(0, T) \quad \forall s < t, s, t \in (0, T) :$

$$\int_s^t (\dot{w}_1 - \dot{w}_2) (\varphi(w_1) - \varphi(w_2)) d\tau \geq c_1 |w_1(\tau) - w_2(\tau)|^2|_s^t \quad (9)$$

$$\begin{aligned} \chi(s) &= K(\tilde{u}(x, s)), \quad s \in \mathbb{C}, \\ s\tilde{u} &= a\tilde{u}_{xx} - b\tilde{u}, \quad \tilde{u}_x(0, t) = 0, \quad \tilde{u}_x(1, t) = 0 \end{aligned} \quad (10)$$

$$\chi(s) = K \left( \frac{ab \cosh(\frac{1}{a}\sqrt{s+bx})}{\sqrt{s+b} \sinh(\frac{1}{a}\sqrt{s+b})} \right) \quad (11)$$

$$\begin{aligned} \exists \Theta > 0 \quad \exists \varepsilon > 0 \quad \exists \lambda > 0 \quad \forall \omega \in \mathbb{R} : \\ \mu_0 \operatorname{Re} \chi(i\omega - \lambda) + \Theta \operatorname{Re} (i\omega \chi(i\omega - \alpha)) &\geq \varepsilon, \end{aligned} \quad (12)$$

$$\exists m > 0 \quad \forall u \in W^{1,2}(0,1) : K(u) \geq m \|u\|_1^2 \quad (13)$$

$\Rightarrow$  assumptions of Theorem 4.1 are satisfied