Bifurcations of invariant measures in discrete-time parameter dependent cocycles

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1. Basic tools for cocycle theory

Let (Q, d) be a complete metric space

A base flow $(\{\tau^t\}_{t\in\mathbb{R}}, (Q, d))$ is defined by a continuous mapping $\tau : \mathbb{R} \times Q \to Q, (t, q) \mapsto \tau^t(q)$ satisfying

1)
$$\tau^{\circ}(\cdot) = \mathrm{id}_Q$$
,

2) $\tau^{t+s}(\cdot) = \tau^t(\cdot) \circ \tau^s(\cdot)$ for each $t, s \in \mathbb{R}$;

A cocycle over the base flow $(\{\tau^t\}_{t\in\mathbb{R}}, (Q, d))$ is defined by the pair $(\{\varphi^t(q, \cdot)\}_{\substack{t\in\mathbb{R}\\q\in Q}}, (M, \rho))$, where (M, ρ) is a metric space and

1)
$$\varphi^t(q, \cdot) : M \to M, \quad \forall \ t \in \mathbb{R}, \quad \forall \ q \in Q$$

2)
$$\varphi^o(q, \cdot) = \mathrm{id}_M, \quad \forall q \in Q,$$

3)
$$\varphi^{t+s}(q, \cdot) = \varphi^t(\tau^s(q), \varphi^s(q, \cdot)), \quad \forall t, s \in \mathbb{R}, \quad \forall q \in Q.$$

Shortly we denote the **cocycle over the base flow** by (τ, φ) . If $q \in Q \mapsto Z(q) \subset M$ is a map, we call $\widehat{Z} = \{Z(q)\}_{q \in Q}$ a **nonautonomous** set. The nonautonomous set $\widehat{Z} = \{Z(q)\}_{q \in Q}$ is said to be **invariant** for the cocycle (τ, φ) if

$$\varphi^t(q, Z(q)) = Z(\tau^t(q))$$
 for all $t \in \mathbb{R}$ and $q \in Q$.

Rokhlin (1964); Kloeden, Schmalfuss (1997)

2. Hausdorff dimension estimates for invariant sets of cocycles

Suppose *H* is a separable Hilbert space, $K \subset H$ is a compact set, $L \in \mathcal{L}(H)$

$$\alpha_k(L) = \sup_{\substack{M \subset H \\ \dim M = k}} \inf_{\substack{u \in M \\ \|u\| = 1}} \|Lu\|, \quad k = 1, 2, \dots$$
$$\omega_k(L) = \begin{cases} \alpha_1(L) \cdot \ldots \cdot \alpha_k(L), & \text{for } k > 0 \\ 1, & \text{for } k = 0. \end{cases}$$

Suppose $d \ge 0$ is an arbitrary number. It can be represented as $d = d_0 + s$, where $d_0 \in \{0, 1, \dots, n-1\}$ and $s \in [0, 1]$. Now we put

$$\omega_d(L) := \begin{cases} \omega_{d_0}(L)^{1-s} \omega_{d_0}(L)^{1+s}, & \text{for } d > 0, \\ 1, & \text{for } d = 0 \end{cases}$$

and we call $\omega_d(L)$ the singular value function of L of order d.

Boichenko, Leonov and Reitmann (2005)

Suppose (τ, φ) is a cocycle:

$$au^t : Q \to Q,$$

 $\varphi^t(\cdot, \cdot) : Q \times H \to H,$
 H is a Hilbert space.

Assumptions:

(A1) The nonautonomous set $\widehat{Z} = \{Z(q)\}_{q \in Q}$ is invariant for the cocycle (φ, τ) .

(A2) For each $q \in Q$ and t > 0 let $\partial_2 \varphi^t(q, \cdot) : H \to H$ be the Fréchet differential of $\varphi^t(q, \cdot)$ w.r.t. the second argument u, which has the following properties:

a) For each $\varepsilon > 0$ and t > 0 the function

$$g_{\varepsilon}(t,q) := \sup_{\substack{u,v \in Z(q) \\ 0 < \|v-u\| \le \varepsilon}} \frac{\|\varphi^t(q,v) - \varphi^t(q,u) - \partial_2 \varphi^t(q,u)(v-u)\|}{\|v-u\|}$$

is bounded on Q and converges to zero as $\varepsilon \to 0$.

b)

$$\sup_{q \in Q} \sup_{u \in Z(q)} \|\partial_2 \varphi^t(q, u)\|_{op} < \infty$$

Theorem 1 (Reitmann, Slepukhin; 2011) Suppose that the assumptions (A1) and (A2) are satisfied and the following conditions hold:

1) There exists a compact set $\widetilde{K} \subset H$ such that

$$\bigcup_{q\in Q} Z(q)\subset \widetilde{K}$$
 .

2) There exists a continuous function $\kappa : Q \times H \to \mathbb{R}_+$, a time s > 0 and a number d > 0 such that

$$Z(q) \subset Z(au^s(q))$$

and

$$\sup_{(q,u)\in Q\times\widetilde{K}}\frac{\kappa(\tau^{s}(q),\varphi^{s}(q,u))}{\kappa(q,u)}\,\omega_{d}(\partial_{2}\,\varphi^{s}(q,u))<1\qquad(1)$$

Then $\dim_H Z(q) \leq d$, $\forall q \in Q$.

Stochastic version: Crauel, Flandoli (1998)

3. Invariant measures for cocycles

Let (Q, \mathfrak{A}, μ) be a probability space. A **metric dynamical system** (MDS) is given by a map $\tau^{(\cdot)}(\cdot) : \mathbb{Z} \times Q \to Q$. For fixed time this is a family of measurable maps which satisfies the group property

1)
$$\tau^0 = \operatorname{id}_Q$$
; 2) $\tau^{t+s} = \tau^t \circ \tau^s, \forall t, s \in \mathbb{Z}.$

 $\{\tau^t\}$ is assumed to be measure preserving, i.e., $\tau^t(\mu) = \mu$. Suppose that (M, \mathfrak{B}) is a measurable space. A **cocycle over the MDS** is given by a map $\varphi : \mathbb{Z}_+ \times Q \times M \to M$ which is for fixed time a $(\mathfrak{A} \otimes \mathfrak{B}, \mathfrak{B})$ -measurable mapping and satisfies for $s, t \in \mathbb{Z}_+$ and almost all $q \in Q$ and $u \in M$ the relations

$$\varphi^{\circ}(q,u) = u; \quad \varphi^{t+s}(q,u) = \varphi^{t}(\tau^{s}(q),\varphi^{s}(q,u)).$$

It is possible to write the cocycle as a skew product flow $(q, u) \mapsto (\tau^t(q), \varphi^t(q, u)) =: \hat{\varphi}^t(q, u).$

An **invariant measure** $\hat{\mu}$ for the cocycle (τ, φ) is a probability measure on $Q \times M$ which is invariant w.r.t. the skew product, i.e. $\forall t \in \mathbb{Z}_+ \hat{\varphi}^t(\hat{\mu}) = \hat{\mu}$ and has the marginal $\pi_Q \hat{\mu} = \mu$ where $\pi_Q : Q \times M \to Q$ is the projection. We can characterize invariant measures by their disintegration $\hat{\mu}(d(q, u)) = \hat{\mu}_q(du)\mu(dq) =$ $\hat{\mu}(q, du)d\mu(q)$. The **Perron-Frobenius operator** *P* is defined by

$$P\hat{\mu}(q, Z(q)) := \hat{\mu}(q, \varphi^{-1}(q, Z(\tau(q)))), \quad q \in Q,$$

where $\varphi^{-1}(q, Z(\tau(q)))$ is the preimage under $\varphi = \varphi^1$ of the set $Z(\tau(q))$.

Arnold (1998); Imkeller, Kloeden (2003)

Example 1 (Baladi, Viana; 1996) $\hat{\varphi} : \hat{I} \to \hat{I}, \hat{I} = \bigcup_{k \ge 0} (\{k\} \times B_k)$ with $B_0 = I$ the unit interval, $\{B_k\}$ subsets of $I, \hat{\varphi}(k, u) = (k + 1, \varphi(u))$ a tower construction, where $\varphi : I \to I$ admits an invariant measure μ absolutely continuous w.r.t. m.

Introduce a cocycle κ : $\widehat{I} \to [0,\infty)$ and the Perron-Frobenius operator

$$P(\hat{g})(k,y) = \sum_{\hat{\varphi}(l,x)=(k,y)} \frac{\kappa(l,x)}{\kappa(k,y)} \frac{\hat{g}(l,x)}{|\varphi'(x)|}$$
(2)

acting at the Banach space $BV(\widehat{I})$ of functions $\widehat{g}: \widehat{I} \to \mathbb{R}$ s. th.

$$\|\widehat{g}\|_{BV} = \operatorname{var} \widehat{g} + \sup |\widehat{g}| + \int |\widehat{g}| \kappa dx < \infty.$$

If ρ is an eigenfunction of *P* associated to the eigenvalue 1 then $\hat{\mu} = \rho \kappa dx$ is an invariant measure for $\hat{\varphi}$. Suppose $\hat{\varphi}$ is invertible. Then (2) reduces with q = k, u = x to

$$P(\hat{g})(\hat{\varphi}(q,u)) = \frac{\kappa(q,u)}{\kappa(\hat{\varphi}(q,u))} \frac{\hat{g}(q,u)}{|\varphi'(u)|}.$$

For the existence of an invariant measure we need

$$\frac{\kappa(q,u)}{\kappa(\hat{\varphi}(q,u))} \frac{1}{|\varphi'(u)|} = 1$$
(3)

or
$$\frac{\kappa(\hat{\varphi}(q,u))}{\kappa(q,u)}|\varphi'(u)| = 1$$
, $\forall (q,u) \in Q \times I$. (4)

For d = n and s = 1 we have $\omega_n(\partial_2 \varphi^1(q, u)) = |\det \partial_2 \varphi^1(q, u)|$. Thus if we consider (1) as equality this condition coincides with (4).

4. The Perron-Frobenius operator on rigged Hilbert spaces

Given a Hilbert space H. A subspace $\mathcal{H} \subset H$ is chosen such that the following holds:

1) ${\cal H}$ has a topology ${\cal T}$ with respect to which it is a locally convex vector space;

2) $(\mathcal{H}, \mathcal{T})$ is continuously and densely embedded into H;

3) $(\mathcal{H}, \mathcal{T})$ is complete and barrelled.

The triplet $\mathcal{H} \subset \mathcal{H} \subset \mathcal{H}'$ where \mathcal{H}' denotes the topological dual of \mathcal{H} is called **rigged Hilbert space** or **Gelfand triplet**. Suppose $A \in \mathcal{L}(\mathcal{H}, \mathcal{H}')$. Then the **adjoint** w.r.t. H is the operator $A^+ \in \mathcal{L}(\mathcal{H}, \mathcal{H}')$ which is given by

$$(A\eta, \vartheta) = (A^+\vartheta, \eta) \quad \forall \, \eta, \vartheta \in \mathcal{H}$$

where (\cdot, \cdot) is the pairing w.r.t. *H*.The operator *A* is **selfadjoint** w.r.t. *H* if $A^+ = A$;

A is normal if $A^+A = AA^+$

Berezansky (1968); Gelfand, Vilenkin (1964)

Example 2 Consider the microwave heating problem

$$w_{tt} - w_{xx} + \sigma(\theta)w_t = 0,$$

$$\theta_t - \theta_{xx} = \sigma(\theta)w_t^2, \ 0 < x < 1, \ t > 0,$$

$$w(0,t) = f_1(t), \ w(1,t) = f_2(t),$$

$$\theta(0,t) = \theta(1,t) = 0, \ t > 0,$$

$$w(x,0) = w_0(x), \ w_t(x,0) = w_1(x),$$

$$\theta(x,0) = \theta_0(x), \ 0 < x < 1.$$
(5)

)

Assumptions:

(A3) σ is locally Lipschitz on $(0, +\infty)$. There exist constants $0 < \sigma_0 \leq \sigma_1$ such that $\sigma_0 < \sigma(z) \leq \sigma_1$ for any z > 0. σ is monotonically decreasing on $(0, +\infty)$.

(A4) $w_0 \in H^1(0,1)$, $w_1 \in L^2(0,1)$, $\theta_0 \in W_3^2(0,1)$, $\theta_0 \ge 0$ a.e. on (0,1).

(A5) $f_1, f_2 \in C^2(\mathbb{R})$ and there exists a constant c such that the functions $|f'_1|, |f'_2|, |f''_1|, |f''_2|$ are bounded on \mathbb{R} by the constant c.

Manoranjan, Yin (2006): For any T > 0 there exists a global weak solution $(w(x,t), \theta(x,t))$ of the problem (5) such that $w \in L^{\infty}(0,T; H^{1}(0,1)), \ \theta \in W_{3}^{2,1}((0,1) \times (0,T))$

Introduce for $t \ge 0$ and $x \in (0, 1)$ the new functions

$$f(x,t) = f_{1}(t)(1-x) + f_{2}(t)x, \ \psi(x,t) = w(x,t) - f(x,t).$$
We get

$$\psi_{tt} - \psi_{xx} + \sigma(\theta)\psi_{t} = f_{tt}(x,t) - f_{t}(x,t)\sigma(\theta),$$

$$\theta_{t} - \theta_{xx} = \sigma(\theta)(\psi_{t} + f_{t})^{2}, \ 0 < x < 1, \ t > 0,$$

$$\psi(0,t) = \psi(1,t) = 0, \ \theta(0,t) = \theta(1,t) = 0, \ t > 0,$$

$$\psi(x,0) = \psi_{0}(x) = w_{0}(x) - f(x,0),$$

$$\psi_{t}(x,0) = w_{1}(x) - f_{t}(x,0),$$
(6)

 $\theta(x, 0) = \theta_0(x), \ 0 < x < 1.$

Define $M = H_0^1(0,1) \times L^2(0,1) \times (W_3^2(0,1) \cap \{\theta | \theta \ge 0, \text{ a.e.}\})$ $\|(\psi, v, \theta)\|_M^2 = \|\psi_x\|_{L^2(0,1)}^2 + \|v\|_{L^2(0,1)}^2 + \|\theta\|_{L^2(0,1)}^2.$

Introduce $Q = \mathbb{R}$, $\tau^t(s) = t + s$, $\varphi^t(s, u_0) = u(t + s, s, u_0)$ where $u(t, s, u_0) = (\psi(\cdot, t), \psi_t(\cdot, t), \theta(\cdot, t))$ is a solution of (6) with $u(s, s, u_0) = u_0$.

Theorem 2 (Kalinin, Reitmann, Yumaguzin, 2011)

System (6) generates a cocycle (τ, φ) which admits a global pullback -B attractor.

Define
$$y = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \begin{pmatrix} w_t(x,t) \\ w(x,t) \\ \theta(x,t) \end{pmatrix}$$
 and consider the evolution

system

$$\frac{dy}{dt} = Ay + B\xi, \ y(0) = y_0 \tag{7}$$

on rigged Hilbert spaces $Y_1 \subset Y_0 \subset Y_{-1}$ with Ξ a Hilbert space, $A: Y_1 \to Y_{-1}, B: \Xi \to Y_{-1}$ linear operators and ξ a nonlinear function.

Let φ be an endomorphism of a measure space (M, \mathfrak{B}) . The evolution operator U is given by the **Koopman operator**

 $(Ug)(x) = g(\varphi(x)),$

where g is a square-integrable function.

The adjoint is the **Perron-Frobenius operator** P. (Lasota, Mackey; 1985)

5. Parameter-dependent cocycles and bifurcations

Let $(Q_{\alpha}, \mathfrak{A}_{\alpha}, \mu_{\alpha})$ be a family of probability spaces depending on a parameter $\alpha \in \mathcal{A}$, where $(\mathcal{A}, \rho_{\mathcal{A}})$ is a metric space. A **parametric metric dynamical system** (PMDS) is given by a family of maps $\tau_{\alpha}^{t}(\cdot) : Q_{\alpha} \to Q\alpha$ which are measurable and satisfy the properties

1) $\tau^0_{\alpha} = \operatorname{id}_{Q_{\alpha}}$; 2) $\tau^{t+s}_{\alpha} = \tau^t_{\alpha} \circ \tau^s_{\alpha}, t, s \in \mathbb{Z}$.

 $\{\tau_{\alpha}^t\}_{\substack{t\in\mathbb{Z}\\\alpha\in\mathcal{A}}}$ is assumed to be measure preserving, i.e. $\tau_{\alpha}^t(\mu_{\alpha}) = \mu_{\alpha}, t\in\mathbb{Z}, \alpha\in\mathcal{A}$. Suppose that (M,\mathfrak{B}) is an other measurable space. A **parametric cocycle** over the PMDS is given by a family of parameter dependent maps $\varphi_{\alpha}^t(\cdot) : Q_{\alpha} \times M \to M$ which are $(\mathfrak{A}_{\alpha} \otimes \mathfrak{B}, \mathfrak{B})$ measurable maps and satisfy the cocycle property. We write the parametric cocycle as a parametric skew product

 $(q,u) \in Q_{\alpha} \times M \mapsto (\tau^{t}_{\alpha}(q), \varphi^{t}_{\alpha}(q,u)) =: \widehat{\varphi}^{t}_{\alpha}(q,u), \ t \in \mathbb{Z}, \ \alpha \in \mathcal{A}.$

A family of invariant measures $\{\hat{\mu}_{\alpha}\}_{\alpha\in\mathcal{A}}$ for the parametric cocycle is a family of probability measures on $Q \times M$ which is invariant w.r.t the parametric skew product, i.e., $\hat{\varphi}^t_{\alpha}(\hat{\mu}_{\alpha}) = \hat{\mu}_{\alpha}$ and $\pi_{Q_{\alpha}}\hat{\mu}_{\alpha} = \mu_{\alpha}$, $\alpha \in \mathcal{A}$.

A parameter value α_0 is called a **bifurcation point** of the family of invariant measures $\{\widehat{\mu}_{\alpha}\}_{\alpha \in \mathcal{A}}$ if this family is not structurally stable at α_0 , i.e., if in any neighborhood of α_0 there are parameter values $\alpha \in \mathcal{A}$ s. th. $\{\widehat{\varphi}_{\alpha_0}^t\}$ and $\{\widehat{\varphi}_{\alpha}^t\}$ are not topologically equivalent.

Arnold (1998)

system

Example 3 The Rényi map $\varphi_{\alpha} : [0, 1] \rightarrow [0, 1]$ is given by $\varphi_{\alpha}(x) = \alpha x \mod 1$ with $\alpha > 1$. This map generates a metric dynamical system $(\{\varphi_{\alpha}^t\}, m)$, where m denotes the Lebesgue measure on the unit interval.

The Koopman operator U_{α} for $\alpha \in \mathbb{N}$ is given by

$$(U_{\alpha}g)(x) = \alpha^{-1} \sum_{i=0}^{\alpha-1} g(\varphi_{\alpha,i}(x)),$$

where $\varphi_{\alpha,i}$ is the inverse of the Rényi map on its *i*-th interval of monotonicity.

(Bandtlow, Antoniou and Suchanecki, 1997)

The associated Perron-Frobenius operator P_{α} of this map

$$P_{\alpha}: L^2(m) \to L^2(m)$$

is given by

$$P_{\alpha}\eta = \frac{d}{dm} \int_{\varphi_{\alpha}^{-1}(\cdot)} \eta \, dm \, ,$$

where $\frac{d}{dm}$ is the Radon-Nikodym derivative w.r.t. m. As positive function spaces \mathcal{H} we can use spaces which are densely and continuously embedded in $L^2(m)$:

- Banach spaces $\mathcal{E}_c(c > 0)$ of entire functions of exponential type c;
- Fréchet spaces $\mathcal{H}(D_r)$ (r > 1) of functions analytic in the open disk with radius r;
- Fréchet space C^{∞} of infinitely differentiable functions on the closed unit interval.

For c < c' and r < r' we have

$$\mathcal{E}_c \hookrightarrow \mathcal{E}_{c'} \hookrightarrow \mathcal{H}(D_{r'}) \hookrightarrow \mathcal{H}(D_r) \hookrightarrow C^\infty \hookrightarrow L^2(m)$$
.

The map under perturbations: $\varphi_{\alpha}(q, u) = \varphi_{\alpha}(u) + q$. Consider the skew product system $\hat{\varphi}_{\alpha} : Q \times I \to Q \times I =: \hat{I}$ with $\hat{\varphi}^{k}(q, u) = (\tau^{k}(q), \varphi^{k}(q, u))$ and the associated function spaces $L^{r}(\hat{I})$.

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