

Embedding of compact invariant sets of dynamical systems on infinite-dimensional manifolds into finite-dimensional spaces

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1 Feedback control systems

Suppose

$$\dot{y} = f(y) \tag{1.1}$$

with a vector function $f : \mathbb{R}^n \rightarrow \mathbb{R}^n$ ("parent flow") is given.

Then (1.1) can be written as *feedback control system*

$$\dot{y} = Ay + B\phi(Cy(t)) , \tag{1.2}$$

where A, B and C are arbitrary $n \times n$ matrices (B and C regular) and $\phi(\sigma) = B^{-1}[f(C^{-1}\sigma) - AC^{-1}\sigma], \sigma \in \mathbb{R}^n$. Consider the more general system

$$\dot{y} = Ay + B\xi(t) , \quad \xi(t) = \phi(Cy(t), \xi_0) \tag{1.3}$$

with the $n \times n, n \times m$ and $l \times m$ matrices A, B and C and the nonlinearity ϕ which can be smooth, piecewise smooth or a hysteresis function.

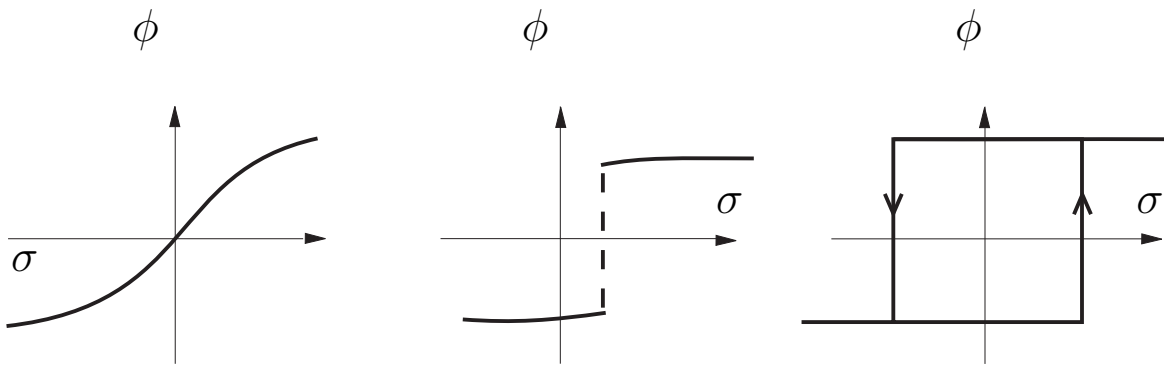


Fig. 1

Example 1.1 dry friction, elasto-plastic deformation (Fig. 1) □

Remark 1.1 (1.3) can also describe an infinite-dimensional system. Suppose $Y_1 \subset Y_0 \subset Y_{-1}$ are densely and continuously embedded Hilbert spaces (*rigged Hilbert space structure*), Ξ and W are also Hilbert spaces,

$$A : Y_1 \rightarrow Y_{-1} , \quad B : \Xi \rightarrow Y_{-1} , \quad C : Y_1 \rightarrow W$$

are bounded linear operators, $\phi : W \rightarrow \Xi$ is a nonlinearity, and the equation

$$\dot{y} = Ay + B\phi(Cy) \tag{1.4}$$

is the *state space realization model* for well-posed input-output (measurement) maps.

- ODE case: $Y_1 = Y_0 = Y_{-1} = \mathbb{R}^n$, $W = \mathbb{R}^s$, $\Xi = \mathbb{R}^r$

- PDE (Boundary control system)

$$Y_0 = L^2(0, 1), Y_1 = W^{1,2}(0, 1), Y_{-1} = Y^*, A : Y_1 \rightarrow Y_{-1},$$

$$(Au, v)_{1,-1} = \int_0^1 (Au)(x)v(x)dx = - \int_0^1 (au_x v_x + bu v)dx,$$

$$\forall u, v \in W^{1,2}(0, 1)$$

$$\Xi = \mathbb{R}, B : \Xi \rightarrow Y_{-1}, B = a\delta(x-1), g : \mathbb{R} \rightarrow \mathbb{R}, a > 0, b > 0 \text{ numbers}$$

$$\left. \begin{aligned} \frac{\partial u}{\partial t} &= au_{xx} - bu, 0 < x < 1, \\ u_x(0, t) &= 0, u_x(1, t) = g(w(t)), u(\cdot, 0) = u_0 \\ g(w(t)) &= Cu(x, t) = \int_0^1 c(x)u(x, t)dx, c \in L^2(0, 1). \end{aligned} \right\} \quad (1.5)$$

- Evolutionary variational inequalities

Suppose $Y_1 \subset Y_0 \subset Y_{-1}$ is a real Hilbert space rigging structure with $A \in \mathcal{L}(Y_1, Y_{-1})$. Assume that Ξ and W are two real Hilbert spaces with scalar products $(\cdot, \cdot)_\Xi$, $(\cdot, \cdot)_W$ and norms $\|\cdot\|_\Xi$, $\|\cdot\|_W$, respectively.

Introduce the linear continuous operators

$$B : \Xi \rightarrow Y_{-1}, \quad C : Y_1 \rightarrow W$$

and define the set-valued map

$$\varphi : \mathbb{R}_+ \times W \rightarrow 2^\Xi$$

and the map

$$\psi : Y_1 \rightarrow \mathbb{R}_+ \cup \{+\infty\}.$$

Consider the *evolutionary variational inequality* (Duvant, Lions, 1976)

$$(\dot{y} - Ay - B\xi, \eta - y)_{-1,1} + \psi(\eta) - \psi(y) \leq 0, \forall \eta \in Y, \quad (1.6)$$

$$w(t) = Cy(t), \xi(t) \in \varphi(t, w(t)), y(0) = y_0 \in Y_0. \quad (1.7)$$

Note that in applications φ is a *material law nonlinearity*, ψ is a *contact-type* or *friction functional* and $w(t) = Cy(t)$ is the *output* of the inequality.

In the contact free case when $\psi = 0$ the evolutionary variational inequality (1.6 - 1.7) is equivalent to an *evolution equation* with a set-valued nonlinearity φ given by

$$\dot{y} = Ay + B\xi \text{ in } Y_{-1}, \quad (1.8)$$

$$w(t) = Cy(t), \xi(t) \in \varphi(t, w(t)), y(0) = y_0 \in Y_0. \quad (1.9)$$

(Likhtarnikov, Yakubovich, 1976; Kantz, Reitmann, 2004)

- Functional differential equations (FDE's or PDE's with delay)

$$\dot{y}(t) = \sum_{k=0}^m A_k y(t+r_k) + B\phi(Cy_t), \quad -r \leq r_m < \dots < r_1 < r_0 = 0, \quad (1.10)$$

$y(0) = h \in H, y_0 = \alpha \in L^2([-r, 0]; H), H$ Hilbert space

$y_t(\cdot) : [-r, 0] \rightarrow H, y_t(\Theta) = y(t + \Theta)$ a.a. $\Theta \in [-r, 0]$

$A_i : \mathcal{D}(A_i) \subset H \rightarrow H, i = 0, 1, \dots, m, Y_0 = L^2([-r, 0]; H) \times H,$

$B \in \mathcal{L}(U, H), U$ Hilbert space

$F : \mathcal{D}(F) \subset Y_0 \rightarrow Y_0$ given by $F(\{\alpha, h\}) := \{\dot{\alpha}, \sum_{k=0}^m A_k h(r_k) + B\phi(C\alpha)\}$

$\mathcal{D}(F) = \{ \{\alpha, h\} \in Y_0 \mid \alpha : [-r, 0] \rightarrow H \text{ absolutely continuous},$

$\dot{\alpha} \in L^2([-r, 0]; H), h = \alpha(0) \in \mathcal{D}(A)\}$ ODE in the *skew-product* Y_0

$$\dot{z}(t) = \bar{A}z(t) + \bar{B}\bar{\phi}(\bar{C}z(t)) \equiv F(z(t)), \quad z(0) = z_0 \in Y_0 \quad (1.11)$$

$$(\{\alpha, h\}, \{\beta, k\})_0 := \int_{-r}^0 (\alpha(\Theta), \beta(\Theta))_H d\Theta + (h, k)_H$$

for $\{\alpha, h\}, \{\beta, k\} \in Y_0$

$$H = \mathbb{R}^n : \dot{y} = \int_{-r}^0 \Gamma(s)y(t+s)ds + A_1 y(t) + A_2 y(t-r) + b\varphi(\sigma(t)),$$

$$\sigma(t) = c^* y(t) + \int_{-r}^0 g^*(s)y(t+s)ds, \quad y(0) = h, y_0 = \alpha,$$

with b and c n -vectors, $g \in L^2([-r, 0]; \mathbb{R}^n),$

$\Gamma \in L^2([-r, 0]; \mathbb{R}^{n \times n}), A_1$ and A_2 $n \times n$ matrices,

$\varphi : \mathbb{R} \rightarrow \mathbb{R}$ s.t. the generalized solutions exist

- Microwave heating process

$$\left. \begin{aligned} w_{tt} - w_{xx} + \sigma(\theta)w_t &= 0, & 0 < x < 1, & t > 0 \\ \theta_t - \theta_{xx} &= \sigma(\theta)w_t^2, & 0 < x < 1, & t > 0 \\ w(0, t) = f_1(t), w(1, t) &= f_2(t), & 0 < x < 1, & t > 0 \\ \theta(0, t) = \theta(1, t) &= 0, & & t > 0 \\ w(x, 0) = w_0(x), w_t(x, 0) &= w_1(x), & 0 < x < 1 & \\ \theta(x, 0) = \theta_0(x). & & 0 < x < 1 & \end{aligned} \right\} \quad (1.12)$$

Suppose $f_1(t) = f_2(t) \equiv 0$. Then we can write (1.12) formally as the system

$$\frac{\partial w}{\partial t} = Aw + B\xi(w_t, \theta)$$

with

$$A = \begin{pmatrix} 0 & I & 0 \\ -\Delta & 0 & 0 \\ -\Delta & 0 & 0 \end{pmatrix}, \quad B = \begin{pmatrix} 0 & 0 \\ -I & 0 \\ 0 & I \end{pmatrix}$$

and

$$\xi(v, \theta) = \begin{pmatrix} \xi_1(v, \theta) \\ \xi_2(v, \theta) \end{pmatrix} = \begin{pmatrix} \sigma(\theta)v \\ \sigma(\theta)v^2 \end{pmatrix}.$$

(Manoranjan, Yin, 2002; Kalinin, Reitmann, Yumaguzin, 2011; Popov, 2011)

- Maxwell-Dirac equation

$$\left. \begin{aligned} (-i\gamma^\mu \partial_\mu + m)\psi &= gv^\mu \gamma_\mu \psi, \\ v_\mu &= (\Delta - \partial_0^2)v_\mu = g\Psi \gamma_\mu \psi, \\ \partial^\mu v_\mu &= 0. \end{aligned} \right\} \quad (1.13)$$

Here the v^μ 's are the components of the electromagnetic vector field, ψ is the Dirac spinor field. The positive definite inner product in spin space is denoted by $\psi^+ \psi$ and Ψ denotes $\psi^+ \gamma^0$. The γ 's are operators in spin space which satisfy $\gamma^\mu \gamma^\nu + \gamma^\nu \gamma^\mu = 2g^{\mu\nu}$ ($g^{00} = 1, g^{11} = -1, g^{\mu\nu} = 0, \mu \neq \nu$).

Existence of solutions (Chadam, 1973)

Attractor type: solitary waves (Komech, Komech, 2010)

Some solution conceptions for (1.3)

- 1) Weak solutions in some Sobolev space
- 2) Classical solutions for differential inclusions
- 3) Filippov solutions, i.e. absolutely continuous functions $y(\cdot)$ which satisfy (1.3) almost everywhere.

H1) For any initial state (1.3) has exactly one Filippov solution on $[0, \infty)$.

2 The reconstruction principle and the cone condition

Let $\gamma = \{y(t) | t \geq 0\}$ be a semi-orbit of (1.3), Π the projection on some plane E (Fig. 2).

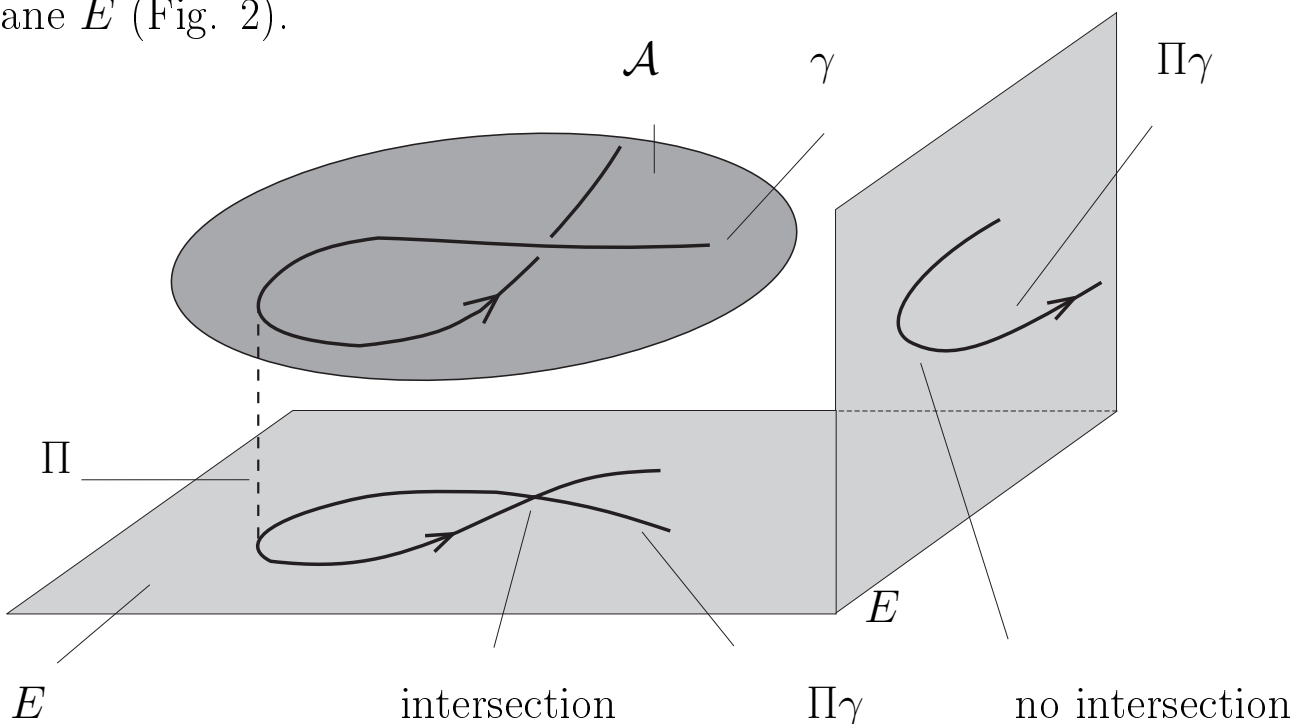


Fig. 2

How to choose a projection $\Pi : \mathbb{R}^3 \rightarrow E \cong \mathbb{R}^2$ such that $\Pi : \gamma \rightarrow \Pi\gamma$ is one-to-one and continuous in \mathcal{A} ?

H2) (*cone condition*) There exist a set $S \subset \mathbb{R}^n$ and an $n \times n$ -matrix $P = P^*$ having 2 negative and $(n - 2)$ positive eigenvalues such that for any two solutions $y_1(\cdot), y_2(\cdot)$ of (1.3) with $y_i(t) \in S, \forall t \geq 0, i = 1, 2$, we

have with $V(y) = y^*Py$ the inequality

$$V(y_1(t) - y_2(t)) \leq 0, \quad \forall t \geq 0 \quad (2.1)$$

(Smith, 1986, Foias et al, 1988, Robinson, 1993)

Geometrical interpretation of the cone condition for $n = 3$

Assume $V(y) = y^*Py$ is a quadratic form satisfying (2.1) along the solutions of (1.3), $K := \{y|V(y) \leq 0\}$ is a 2-dimensional cone, $\mathbb{R}^3 \setminus K$ is a 1-dimensional cone (Fig.3). Let l be the direction of the main axis of $\mathbb{R}^3 \setminus K$ with $l^*Pl > 0$, E is the orthogonal to l plane through the origin, Π is the orthogonal projection on E .

Suppose that $y_1(\cdot), y_2(\cdot)$ are two arbitrary distinct solutions of (1.3) in S , i.e. $y_1(t) \neq y_2(t) \quad \forall t \geq 0, y_1(t), y_2(t) \in S, \quad \forall t \geq 0$. From (2.1) we have $V(y_1(t) - y_2(t)) \leq 0, \quad \forall t \geq 0$, i.e. $y_1(t) - y_2(t) \in K, \quad \forall t \geq 0$.

Then

$$\Pi y_1(t) \neq \Pi y_2(t), \quad \forall t \geq 0. \quad (2.2)$$

Assume the opposite, i.e. assume that

$$\exists t_0 \geq 0 : \Pi y_1(t_0) = \Pi y_2(t_0). \quad (2.3)$$

It follows from (2.3) that $\Pi [y_1(t_0) - y_2(t_0)] = 0$, i.e. the point $y_1(t_0) - y_2(t_0)$ is projected under Π into 0. But then there exists a $k \neq 0$ such that $y_1(t_0) - y_2(t_0) = kl$. Consequently we have $V(kl) = k^2 l^*Pl > 0$, a contradiction to the fact that $V(y_1(t_0) - y_2(t_0)) \leq 0$.

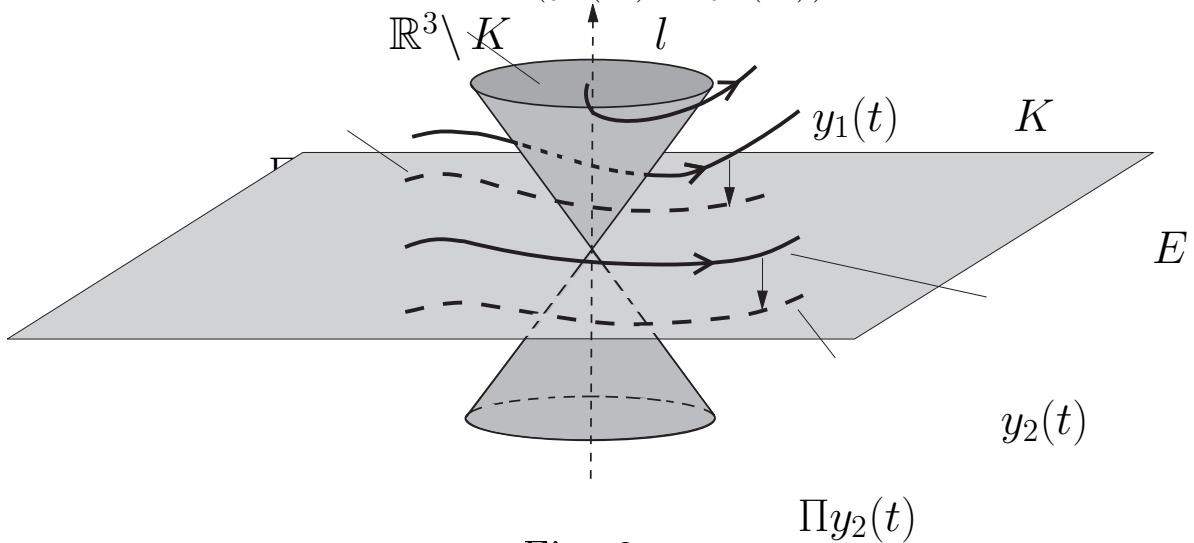


Fig. 3

3 Frequency-domain methods

Suppose A, B and C are matrices of order $n \times n, n \times m$ and $l \times n$, respectively, $F(x, \xi)$ is a *Hermitian form* on $\mathbb{C}^n \times \mathbb{C}^m$, i.e. a quadratic form which takes only real values. The pair (A, B) is called *stabilizable* if there exists an $n \times m$ matrix D such that $A + BD$ is Hurwitzian, i.e. has only eigenvalues with negative real part.

Theorem 3.1 (*Frequency theorem; Yakubovich, 1962; Kalman, 1963*)

Let the pair (A, B) be stabilizable and $\det(i\omega I - A) \neq 0, \forall \omega \in \mathbb{R}$.

a) For the existence of a real symmetric $n \times n$ -matrix P satisfying the Riccati inequality

$$\begin{aligned} 2 \operatorname{Re} x^* P (Ax + B\xi) + F(x, \xi) &< 0, \\ \forall x \in \mathbb{C}^n \quad \forall \xi \in \mathbb{C}^m, |x| + |\xi| &\neq 0 \end{aligned} \quad (3.1)$$

it is necessary and sufficient that the frequency-domain condition

$$\begin{aligned} F((i\omega I - A)^{-1} B \xi, \xi) &< 0, \\ \forall \xi \in \mathbb{C}^m, \xi \neq 0 \quad \forall \omega \in \mathbb{R} \end{aligned} \quad (3.2)$$

is satisfied.

b) A matrix $P = P^*$ satisfying (3.1) can be computed in a finite number of steps.

Consider the system

$$\dot{y} = Ay + B\phi(Cy(t)), \quad (3.3)$$

where A, B and C are matrices of order $n \times n, n \times 1$ and $1 \times n$, respectively. Introduce the *transfer function* $\chi(z) = C(zI - A)^{-1}B$ for $z \in \mathbb{C} : \det(zI - A) \neq 0$.

$\phi : \mathbb{R} \rightarrow \mathbb{R}$ satisfies the following condition:

(H3) There exist parameters $\mu_1 < 0 < \mu_2$ such that

$$\mu_1(\sigma_1 - \sigma_2)^2 \leq [\phi(\sigma_1) - \phi(\sigma_2)](\sigma_1 - \sigma_2) \leq \mu_2(\sigma_1 - \sigma_2)^2 \quad \forall \sigma_1, \sigma_2 \in \mathbb{R} \quad (3.4)$$

Remark 3.1 If ϕ is C^1 the condition (3.4) can be written in the following way:

(H3)' There exist parameters $\mu_1 < 0 < \mu_2$ such that

$$\mu_1 \leq \phi'(\sigma) \leq \mu_2, \quad \forall \sigma \in \mathbb{R} \quad (3.4)'$$

□

Theorem 3.2 Suppose that for ϕ from (3.3) the condition **(H3)** is satisfied and there exists a $\lambda > 0$ such that the following holds:

- 1) The pair $(A + \lambda I, B)$ is stabilizable ;
- 2) The matrix $A + \lambda I$ has exactly two eigenvalues with positive real part and $(n - 2)$ with negative real part;
- 3) $\text{Re} [1 + \mu_1 \chi(i\omega - \lambda)] [1 + \mu_2 \chi(i\omega - \lambda)]^* > 0, \quad \forall \omega \in \mathbb{R};$

} (Gap condition)

Then there exists an $n \times n$ -matrix $P = P^*$ having 2 negative and $(n - 2)$ positive eigenvalues, and a number $\varepsilon > 0$ such that with the function $V(y) = y^* P y$ the inequality

$$\frac{d}{dt} V(y_1(t) - y_2(t)) + \lambda V(y_1(t) - y_2(t)) - \varepsilon |y_1(t) - y_2(t)|^2, \quad \forall t \geq 0 \quad (3.5)$$

(Squeezing property)

is satisfied for any two solutions $y_1(\cdot), y_2(\cdot)$ of (3.3).

Geometrical interpretation of the frequency-domain condition

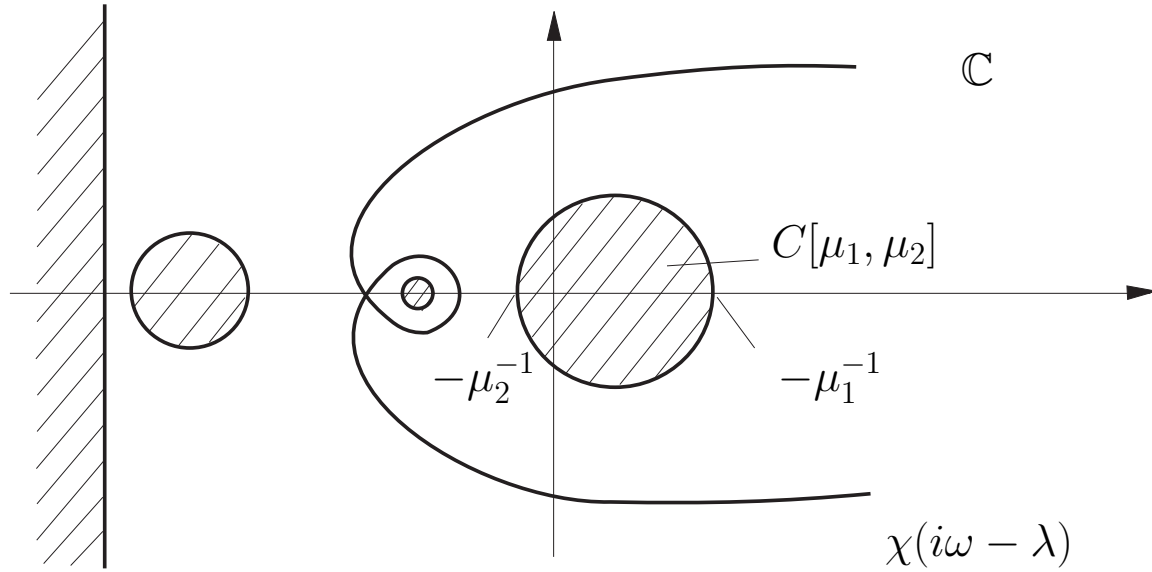


Fig. 4

4 Amenable solutions and essential modes

Definition 4.1 (*R. A. Smith, 1987*) Suppose $\lambda > 0$ is a number. A solution $y(\cdot)$ of (1.3) is called amenable if there exists a number $\tau \in \mathbb{R}$ such that $y(t) \in S$, $\forall t \leq \tau$, and $\int_{-\infty}^{\tau} e^{2\lambda t} |y(t)|^2 dt < +\infty$.

Remark 4.1 If (1.3) has a compact attractor then all solutions inside the attractor are amenable. \square

Theorem 4.1 Suppose that the conditions of Theorem 3.2 are satisfied with a parameter $\lambda > 0$ and $P = P^*$ is the $n \times n$ matrix satisfying

$$2y^*P[(A + \lambda I)y + B\psi] + (\mu_2 Cy - \psi)(\psi - \mu_1 Cy) \leq -\varepsilon[|y|^2 + |\psi|^2] \\ \forall y \in \mathbb{R}^n, \forall \psi \in \mathbb{R}.$$

and having 2 negative and $(n - 2)$ positive eigenvalues.

Choose a matrix $Q = Q^*$ of order $n \times n$ such that

$$Q^*PQ = \begin{pmatrix} -1 & & & & \\ & -1 & & & \\ & & +1 & & \\ 0 & & & \ddots & \\ & & & & +1 \end{pmatrix}$$

and define the linear map $\Pi : \mathbb{R}^n \rightarrow \mathbb{R}^2$ by $\Pi y := u$ where $\begin{pmatrix} u \\ v \end{pmatrix} = Q^{-1}y$ with $u \in \mathbb{R}^2$,

$v \in \mathbb{R}^{n-2}$. Then if \mathcal{A} is the set of amenable solution of (3.3) the map

$$\Pi : \mathcal{A} \rightarrow \Pi \mathcal{A} \tag{4.1}$$

is a homeomorphism, i.e. one-to-one and bicontinuous.

Definition 4.2 (*O. Ladyzhenskaya, 1987*) Suppose that (1.4) has in the (infinite-dimensional) phase-space Y_0 an attractor \mathcal{A} and a finite-dimensional projector Π with the following property: For any two orbits γ_1, γ_2 of the attractor \mathcal{A} the condition $\Pi \gamma_1 = \Pi \gamma_2$ implies $\gamma_1 = \gamma_2$. Then we say that the number of essential or determining modes of (1.4) for \mathcal{A} is finite.

Corollary 4.1 Suppose that the conditions of Theorem 3.2 are satisfied and (3.3) has a compact attractor \mathcal{A} . Then the number of essential modes for \mathcal{A} is two.

Remark 4.2 In many cases in the system $\dot{y} = Ay + B\phi(Cy)$ (1.4) we have a symmetric $A = A^* : Y_1 \rightarrow Y_{-1}$. If the embedding $Y_1 \subset Y_{-1}$ is completely continuous then the operator A has a system of eigenfunctions (modes) $\{w_j\}$ associated to eigenvalues $\{\lambda_j\}$ by $Aw_j = \lambda_j w_j, w_j \in Y_1, \lambda_i < \lambda_{i+1}, \lambda_i \rightarrow +\infty, (w_j, w_k) = \delta_j^k$ such that $\{w_j\}$ is a basis of Y_1 , i.e. any element y can be written as $y = \sum y_j w_j, \sum y_j^2 < \infty$.

Then $\Pi y := (y_1, y_2) \in \mathbb{R}^2$ or, more general, $\Pi y = (y_1, \dots, y_i) \in \mathbb{R}^i$ is a finite-dimensional projection. Physically this means that the *total energy* of an orbit is dominated by the energy of the first i modes. \square

5 Lipschitz manifolds and the extension procedure

Consider (3.3) under the assumptions of Theorem 4.1 and let

$$h : \Pi \mathcal{A} \rightarrow \mathcal{A} \quad (5.1)$$

be the inverse map of $\Pi : \mathcal{A} \rightarrow \Pi \mathcal{A}$, (4.1), where \mathcal{A} is again the set of amenable solutions.

It follows from

$$2 |\Pi p_1 - \Pi p_2|^2 \geq |Q^{-1}(p_1 - p_2)|^2 \geq |\Pi p_1 - \Pi p_2|^2 \quad \forall p_1, p_2 \in \gamma_1, \gamma_2.$$

that

$$2 |u_1 - u_2|^2 \geq |Q^{-1}(h(u_1) - h(u_2))|^2 \geq |u_1 - u_2|^2, \quad \forall u_1, u_2 \in \Pi \mathcal{A}. \quad (5.2)$$

If $y(\cdot)$ is an amenable solution of (3.3) then $u(t) := \Pi y(t)$ is the solution of the

2-dimensional *reduced* or *observation ODE*

$$\dot{u} = \underbrace{\Pi f(h(u))}_{=:g(u)} \quad (f(y) = Ay + B\phi(Cy)). \quad (5.3)$$

The reduced vector field g is defined only on the closed set $\Pi \mathcal{A} \subset E \cong \mathbb{R}^2$, since h is defined only on $\Pi \mathcal{A}$. Can we extend h to a Lipschitz continuous map

$$\tilde{h} : E \cong \mathbb{R}^2 \rightarrow \mathbb{R}^n (Y_0) ?$$

Assume for a moment that this is possible. Then it holds:

1) $\tilde{g} := \Pi (f(\tilde{h}))$ is a Lipschitz vector field on $E \cong \mathbb{R}^2$ if f is Lipschitz : $\tilde{g} = \Pi \circ f \circ \tilde{h}$.

It follows that all solutions of (3.2) exist and are unique. The *observation ODE (5.2) can be used for the reconstruction of the set \mathcal{A} of (3.3).*

2) The set \mathcal{A} of amenable solutions of (3.3) lies in the set

$$\mathcal{M} := \{y \in \mathbb{R}^n | y = \tilde{H}(u), u \in \mathbb{R}^2\} . \quad (5.4)$$

(Y_0) (\mathbb{R}^m)

Since \tilde{h} is Lipschitz the set (5.4) is a 2-dimensional (m -dimensional) Lipschitz manifold. If \mathcal{A} is the global attractor the set \mathcal{M} attracts all orbits of (3.3) from $\mathbb{R}^n(Y_0)$. In this case \mathcal{M} is called the *inertial manifold* of (3.3) (Foias et al, 1988, Robinson, 1993) .

Theorem 5.1 (Stein's extension theorem Stein, 1970)

Let X be a closed subset of \mathbb{R}^m , $H(= Y_0)$ be a Hilbert space, and $h : X \rightarrow H$ be a continuous function.

Then there is a continuous extension $\tilde{h} : \mathbb{R}^m \rightarrow H$ and there exists a $K = K(m)$ such that if $|h(x) - h(y)| \leq C|x - y|, \forall x, y \in X$, then $|\tilde{h}(x) - \tilde{h}(y)| \leq KC|x - y|, \forall x, y \in \mathbb{R}^m$.

Corollary 5.1 *Under the conditions of Theorem 4.1 the reduced vector field (5.2) can be extended to a Lipschitz vector field in $E \cong \mathbb{R}^2$. Any amenable solution y of the infinite-dimensional vector field*

$\dot{y} = Ay + B\phi$ in the phase space Y_0 can be represented as $y = \tilde{h}(u(t))$, where $u(t)$ is the unique solution of the reduced equation (5.2) with initial state $u(0) = \Pi y(0)$.

6 Constructing a reduced system from measurements

Suppose

$$\dot{y} = f(y) \quad (6.1)$$

is a given (unknown) dissipative system in \mathbb{R}^n with attractor \mathcal{A} .

Step 1: Choice of the linear part

Choose a number $\lambda > 0$ and matrices A, B and C of order $n \times n, n \times 1$ and $1 \times n$, respectively, such that $(A + \lambda I, B)$ is stabilizable, and $A + \lambda I$ has $2(m)$ eigenvalues with positive real part and $n - 2$ eigenvalues with negative real part.

Step 2: Reconstruction of the class of nonlinearities

Calculate on $[0, T]$ the linear semigroup $S(t) = e^{At}$ with A from Step 1. Take an $\varepsilon < 0$ (tolerance), a natural number N and observe near the attractor the solutions $y_i(\cdot), i = 1, 2, \dots, N$, of (6.1) on $[0, T]$. Find for any $i = 1, 2, \dots, N$ a solution $\phi_i \in L^\infty(0, T; \mathbb{R}^n)$ of the linear inequality

$$\sup_{t \in [0, T]} |Cy_i(t) - CS(t)y_i(0) - \int_0^t CS(t-s)B\phi_i(s)ds| < \varepsilon. \quad (6.2)$$

It follows that $\phi_i(t) \approx \phi(Cy_i(t))$ in the sense of $L^2(0, T)$, where $\dot{y}_i(t) = Ay_i + B\phi(Cy_i(t))$ on $[0, T]$.

Determine two constants $-\infty \leq \mu_1 < \mu_2 \leq +\infty$ ($\mu_2 < +\infty$ if $\mu_1 = -\infty$ and $\mu_1 > -\infty$ if $\mu_2 = +\infty$) such that

$$\begin{aligned} \mu_1 [C(y_i(t) - y_j(t))]^2 &\leq [\phi_i(t) - \phi_j(t)] C [y_i(t) - y_j(t)] \\ &\leq \mu_2 [C(y_i(t) - y_j(t))]^2, \quad i, j = 1, \dots, N \quad t \in [0, T]. \end{aligned} \quad (6.3)$$

Step 3: Graphic test of the frequency-domain / gap condition

Compute the frequency-domain characteristic

$\chi(i\omega - \lambda) = C((i\omega - \lambda)I - A)^{-1}B$ and compare with the circle $C[\mu_1, \mu_2]$ with $\mu_1 < \mu_2$ from Step 2 (Fig. 5).

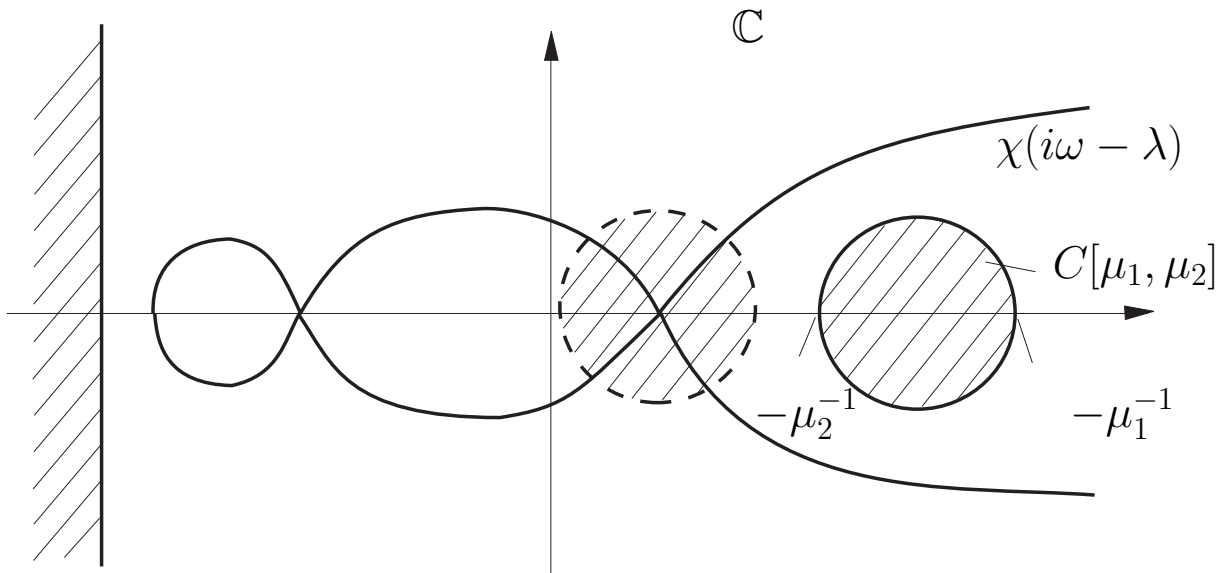


Fig. 5

If there is no intersection between $\chi(i\omega - \lambda)$ and $C[\mu_1, \mu_2]$ go to Step 4. In other case change A, B, C or m and begin again with Step 1. *Step 4:*

Calculation of a homeomorphism $\Pi : \mathcal{A} \rightarrow \Pi \mathcal{A}$

Find with A, B, C from Step 1 and $\mu_1 < \mu_2$ from Step 3 an $n \times n$ matrix $P = P^*$ of the matrix inequality

$$2y^*P[(A + AI)y + B\psi] + (\mu_2Cy - \psi)(\psi - \mu_1Cy) < 0, \\ \forall y \in \mathbb{R}^n, \forall \psi \in \mathbb{R}, |y| + |\psi| \neq 0. \quad (6.4)$$

Such a solution exists by the frequency theorem and is computable in a finite number of steps. Any solution $P = P^*$ of (6.3) has 2 negative and $n - 2$ positive eigenvalues. Define a matrix $Q = Q^*$ through

$$Q^*PQ = \begin{pmatrix} -1 & & & \\ & -1 & & 0 \\ & & +1 & \\ 0 & & & \ddots \\ & & & & +1 \end{pmatrix}. \text{ Then the projection is } \Pi : \mathbb{R}^n \rightarrow \mathbb{R}^2$$

defined by $\Pi y = u, y \in \mathbb{R}^n, u \in \mathbb{R}^2, v \in \mathbb{R}^{n-2}$, s.th. $\begin{pmatrix} u \\ v \end{pmatrix} = Q^{-1}y$.

It follows from Theorem 4.1 that if \mathcal{A} is the amenable set of (6.1) then $\Pi : \mathcal{A} \rightarrow \Pi \mathcal{A}$ is a homeomorphism.

Step 5: Determination of a reduced ODE for the full equation

Let $\Pi : \mathcal{A} \rightarrow \Pi \mathcal{A}$ be the homeomorphism from Step 4. Determine a reduced 2-dimensional ODE $\dot{u} = \underbrace{\Pi f(\tilde{h}(u))}_{\tilde{g}(u)}$ from the observations $\Pi y_i(t)$,

where $y_i(t)$ are arbitrary solutions of (6.1) near the attractor and use constructively the extension theorem of Stein to extend this vector field from the closed set $\Pi \mathcal{A} \subset E \cong \mathbb{R}^2$ to a Lipschitz vector field on the whole E .

7 When is a given linear projection a homeomorphism on the attractor?

Suppose

$$\dot{y} = f(y) \quad (7.1)$$

is on ODE in \mathbb{R}^n . \mathcal{A} is the set of amenable solutions and $\Pi : \mathbb{R}^n \rightarrow \mathbb{R}^k$ is a given linear projection. Under what conditions is $\Pi : \mathcal{A} \rightarrow \Pi\mathcal{A}$ a homeomorphism?

Write (7.1) again in the form

$$\dot{y} = Ay + B\phi(\Pi y), \quad (7.2)$$

where A and B are $n \times n$ and $n \times m$ matrices, and $B\phi : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is defined by $B\phi(\Pi y) := f(y) - Ay$. Assume that $f(0) = 0$ and the solutions of (7.1) exist on \mathbb{R}_+ and are unique. Let $K \subset \mathbb{R}^n$ be an invariant and absorbing

cone for (7.2) having the property

$$K \cap \{y \in \mathbb{R}^n \mid \Pi y = 0\} = \{0\}. \quad (7.3)$$

If (7.3) is satisfied then $\Pi : \mathcal{A} \rightarrow \Pi\mathcal{A}$ is a homeomorphism.

(H3)” There exists a $k \times m$ matrix M such that

$$0 \leq (\Pi(y_1 - y_2))^* M [\phi(\Pi y_1) - \phi(\Pi y_2)], \quad \forall y_1, y_2 \in \mathbb{R}^n.$$

Define the Hermitian form $F_{\mathbb{C}}(y, \xi) := \text{Re}(y^* \Pi^* M \xi)$, $y \in \mathbb{C}^n$, $\xi \in \mathbb{C}^m$, and the transfer matrix $\chi(i\omega) := (i\omega I - A)^{-1} B$.

Theorem 7.1 *Suppose that (H3)” is satisfied and there exists a $\delta > 0$ such that the following holds:*

- 1) *The pair $(A + \lambda I, B)$ is stabilizable ;*
- 2) *The matrix $A + \lambda I$ has k eigenvalues with positive real part and $n - k$ with negative real part ;*
- 3) *$\text{Re } F_{\mathbb{C}}(\chi(i\omega - \lambda)\xi, \xi) < 0$, $\forall \xi \in \mathbb{C}^m, \xi \neq 0, \forall \omega \in \mathbb{R}$;*
- 4) *$\xi^* B^* \Pi^* M \xi \geq 0$, $\forall \xi \in \mathbb{R}^m$.*

Then there exists a symmetric $n \times n$ matrix P having k negative and $n - k$ positive eigenvalues such that the following holds:

- a) The k -dimensional cone $K := \{y \in \mathbb{R}^n | y^* P y \leq 0\}$ is positively invariant for all solutions of (7.1);
- b) $K \cap \{y \in \mathbb{R}^n | \Pi y = 0\} = \{0\}$;
- c) K absorbs \mathcal{A} and, consequently, $\Pi : \mathcal{A} \rightarrow \Pi \mathcal{A} \subset \mathbb{R}^k$ is a homeomorphism.

(Kantze, Reitmann, 2004)

8 Dynamical systems on Banach manifolds

Let \mathcal{M} be an *infinite-dimensional Banach manifold* and $F : \mathcal{M} \rightarrow T\mathcal{M}$ be a smooth vector field on \mathcal{M} .

Let us consider the equation

$$\dot{u} = F(u)$$

and the dynamical system on \mathcal{M} : $(\{\varphi^t\}_{t \in \mathbb{R}}, \mathcal{M})$, $\varphi^t(u_0) \equiv u(t, u_0)$, $u(0, u_0) = u_0$.

Let $u_0 \in \mathcal{M}$ be a given point and $\{\varphi^t(u_0)\}_{t \geq 0}$ be the associated trajectory

A map $h : \mathcal{M} \rightarrow \mathbb{R}$ is called *observation function*

Let T be the interval between the measurements. Then we get the sequence $z_0 = h(u_0)$, $z_1 = h(\varphi^T(u_0))$, \dots , $z_i = h(\varphi^{iT}(u_0))$, \dots

An *embedding function* is a map

$$\Phi_{\varphi, h}(u) := (h(u), h(\varphi^T(u)), \dots, h(\varphi^{(k-1)T}(u))), \quad u \in \mathcal{M}$$

(Takens, 1981)

Theorem 8.1 [Takens, 1981] *Let \mathcal{M} be a compact manifold of dimension n . Let $k \in \mathbb{N}$, such that $k \geq 2n + 1$. Then the set (φ, h) of pairs for which the embedding function $\Phi_{\varphi, h}$ is a topological embedding is open and dense in the space $\text{Diff}^r(\mathcal{M}) \times C^r(\mathcal{M}, \mathbb{R})$ for $r \geq 1$.*

Theorem 8.2 [Robinson, 2005] *Let H be a Hilbert space and \mathcal{A} be a compact set whose fractal dimension satisfies $\dim_f(\mathcal{A}) < d$, $d \in \mathbb{N}$, and which has thickness τ . Choose $k > (2 + \tau)d$, and suppose further that \mathcal{A} is an invariant set for a Lipschitz map $\varphi : H \rightarrow H$, such that*

- *the set Γ of points in \mathcal{A} such that $\varphi(x) = x$ satisfies $\dim_f(\Gamma) < 1/2$, and*
- *\mathcal{A} contains no periodic orbits of φ of period $2, \dots, k$.*

Then a prevalent set of Lipschitz maps $h : H \rightarrow \mathbb{R}^k$ make the embedding $\Phi_{\varphi, h} : H \rightarrow \mathbb{R}^k$ one-to-one on \mathcal{A} .

Theorem 8.3 [Okon, 2002] *Let \mathcal{M} be a C^∞ - manifold with one chart $x : \mathcal{M} \rightarrow U$ where $U \subset H$ is bounded and convex, H is a Banach space. Let ρ_x be the metric which is induced by the chart x and let $K \subset \mathcal{M}$ be a compact with $\dim_f(K) \leq d$, $N > 2d$, and $\alpha < (N - 2d)/(N(1 + d))$. Then the set of all $\psi \in C_b^k(\mathcal{M}, \mathbb{R}^N)$ such that*

$$\exists C > 0 \quad \forall v, w \in K : C|\psi(v) - \psi(w)|^\alpha \leq \rho_x(v, w)$$

is prevalent in $C_b^k(\mathcal{M}, \mathbb{R}^N)$.

Let $\dim_{cor}(X) = \lim_{\varepsilon \rightarrow 0} \frac{\ln C(\varepsilon)}{\ln \varepsilon}$ be the correlation dimension. Here $C(\varepsilon)$ is the correlation integral

$$C(\varepsilon) = \lim_{N \rightarrow \infty} \frac{1}{N^2} \sum_{i, j=1}^N \Theta(\varepsilon - \|x_i - x_j\|),$$

where x_i are vectors from X and $\Theta(x)$ is the Heaviside function:

$$\Theta(x) = \begin{cases} 1, & x \geq 0 \\ 0, & x < 0. \end{cases}$$

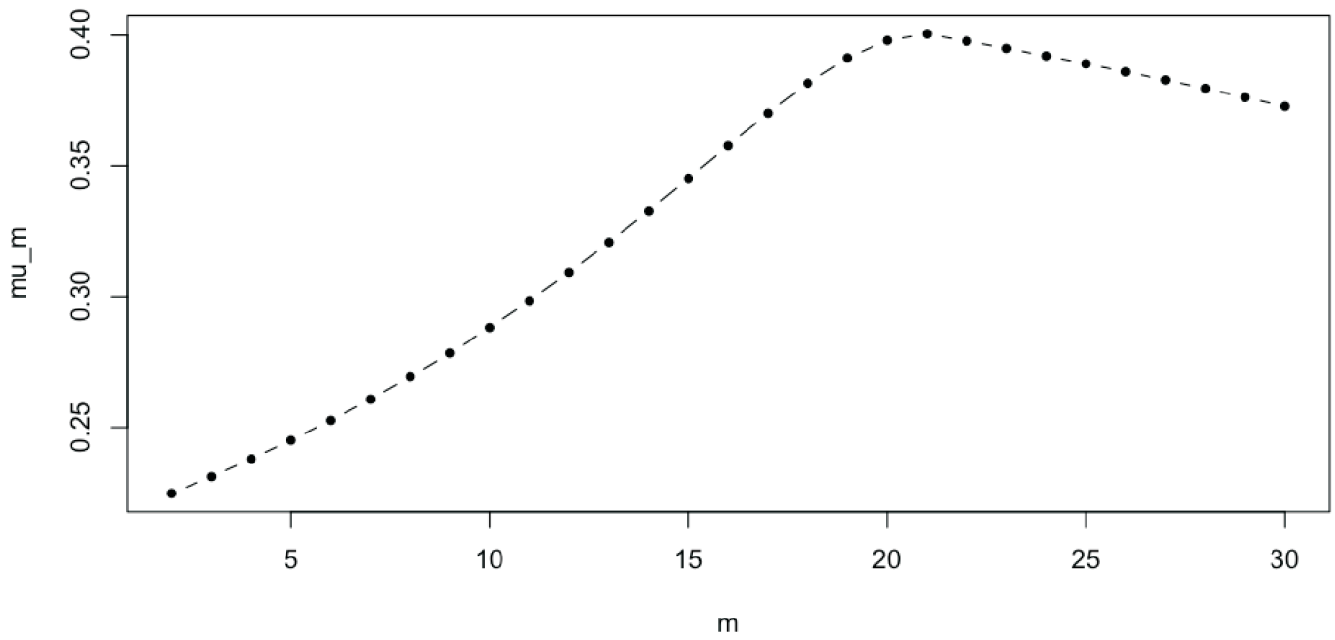


Fig. 6 The estimation of the correlation dimension for the Microwave heating process (1.12)

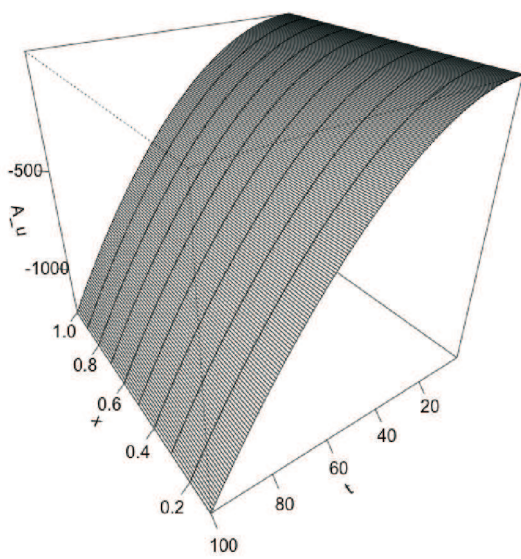


Fig. 7 Solution of Maxwell-Dirac equation (Das, 1993) A_u

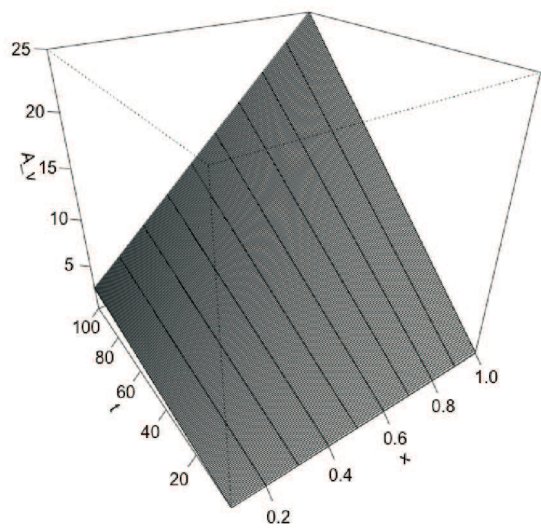


Fig. 8 Solution of Maxwell-Dirac equation (1.13) A_v

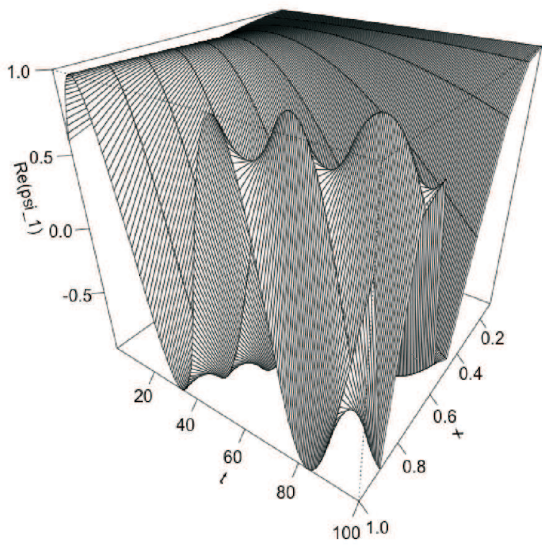


Fig. 9 Solution of Maxwell-Dirac equation
(1.13) $\text{Re}(\psi_1)$

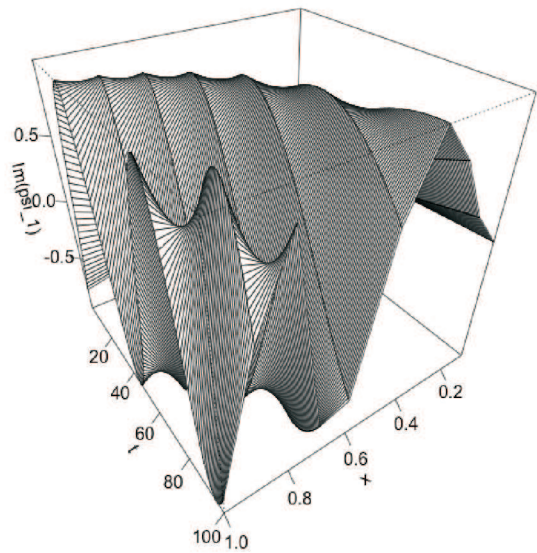


Fig. 10 Solution of Maxwell-Dirac equation
(1.13) $\text{Im}(\psi_1)$

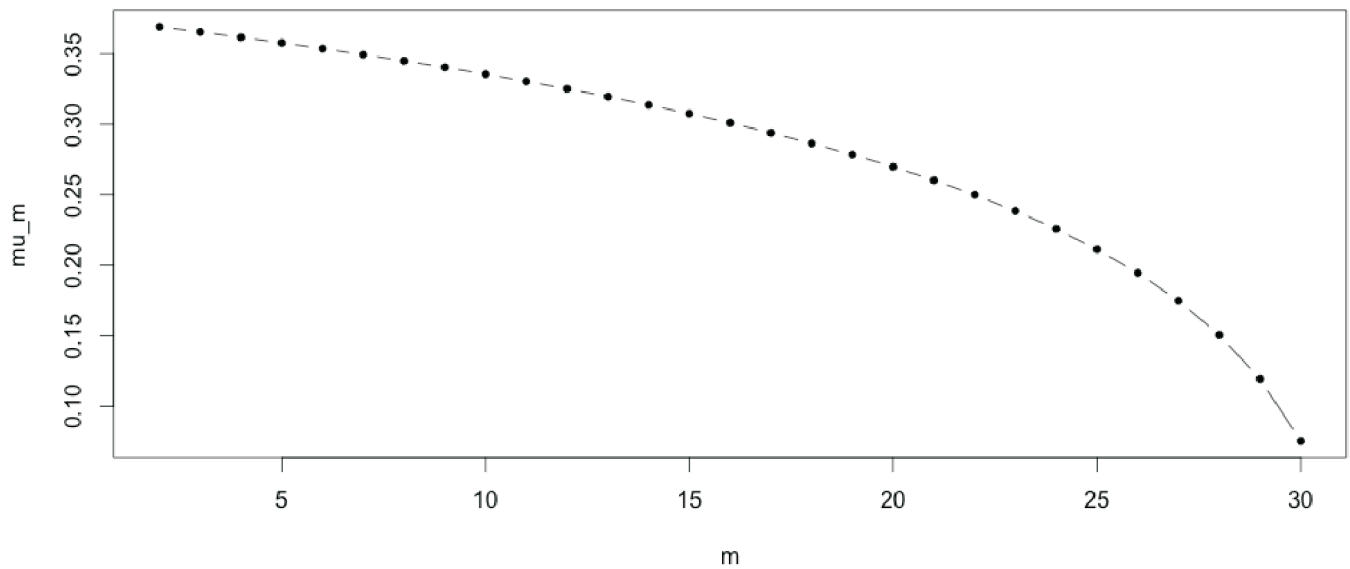


Fig. 11 The estimation of the correlation dimension for the
Maxwell-Dirac equation (1.13)

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Proof of Theorem 3.2 Suppose $y_1(\cdot), y_2(\cdot)$ are two arbitrary solutions of (3.3). Then $y := y_1 - y_2$ is a solution of

$$\dot{y} = Ay + B\psi \text{ with } \psi(t) := \phi(\sigma_1(t)) - \phi(\sigma_2(t)),$$

$$\sigma_i(t) := Cy_i(t), i = 1, 2.$$

By assumption **(H3)** we have with $\sigma = \sigma_1 - \sigma_2$ the inequality

$$\mu_1\sigma(t)^2 \leq \psi(t)\sigma(t) \leq \mu_2\sigma(t)^2, \forall t \geq 0. \quad (8.1)$$

Because of 1) and 3) Theorem 3.1 is applicable with the Hermitian form $F(y, \xi) = \text{Re}[(\mu_2Cy - \xi)(\xi - \mu_1Cy)^*]$ (Fig. 4). It follows that there exist an $n \times n$ -matrix

$P = P^*$ and a number $\varepsilon > 0$ such that

$$2y^*P[(A + \lambda I)y + B\psi] + (\mu_2Cy - \psi)(\psi - \mu_1Cy) \leq -\varepsilon[|y|^2 + |\psi|^2] \\ \forall y \in \mathbb{R}^n, \forall \psi \in \mathbb{R}. \quad (8.2)$$

For $\psi = 0$ we get from (8.2) the inequality

$$2y^*P(A + \lambda I)y - \mu_1\mu_2(Cy)^2 \leq -\varepsilon|y|^2, \forall y \in \mathbb{R}^n. \quad (8.3)$$

Since $\mu_1\mu_2 < 0$ inequality (8.3) implies that

$$y^*P(A + \lambda I)y + y^*(A + \lambda I)^*Py < 0, \forall y \in \mathbb{R}^n \quad y \neq 0. \quad (8.4)$$

From (8.4) it follows by Lyapunov's theorem that the matrix P has exactly 2 negative and $(n - 2)$ positive eigenvalues, since $A + \lambda I$ has 2 eigenvalues with positive real part and $(n - 2)$ eigenvalues with negative real part.

Putting in (8.2) $y = y_1 - y_2$, $\psi = \phi(Cy_1) - \phi(Cy_2)$ and using the fact that

$$[\mu_2C(y_1 - y_2) - (\phi(Cy_1) - \phi(Cy_2))] [(\phi(Cy_1) - \phi(Cy_2)) - \mu_1C(y_1 - y_2)] \geq 0,$$

we derive from (8.2) the inequality

$$\frac{d}{dt}V(y_1(t) - y_2(t)) + 2\lambda V(y_1(t) - y_2(t)) \leq -\varepsilon|y_1(t) - y_2(t)|^2, \forall t \geq 0. \quad \blacksquare$$

Proof of Theorem 8.3 (See also Smith, 1986 $\frac{d}{dt}[e^{2\lambda t}V(y_1 - y_2)] \leq -2\varepsilon e^{2\lambda t}|y_1 - y_2|^2$, $\forall t \leq \tau$, if $y_1, y_2 \in S$. Integration on $[\Theta, \tau]$ gives

$$e^{2\lambda\tau}V(y_1(\tau) - y_2(\tau)) \leq e^{2\lambda\Theta}V(y_1(\Theta) - y_2(\Theta)) - 2\varepsilon \int_{\Theta}^{\tau} e^{2\lambda t}|y_1(t) - y_2(t)|^2 dt. \quad (8.5)$$

Since $e^{\lambda t}|y_1(t)|, e^{\lambda t}|y_2(t)|$ are in $L^2(-\infty, \tau)$ the function $e^{\lambda t}|y_1 - y_2|$ is also in $L^2(-\infty, \tau)$.

It follows that there exists a sequence of times $\Theta_\nu \rightarrow -\infty$ as $\nu \rightarrow \infty$ with

$|y_1(\Theta_\nu) - y_2(\Theta_\nu)|e^{\lambda\Theta_\nu} \rightarrow 0$. Putting in (8.5) $\Theta = \Theta_\nu$ and assuming $\nu \rightarrow \infty$ we get

$$e^{2\lambda\tau}V(y_1(\tau) - y_2(\tau)) \leq -2\varepsilon \int_{-\infty}^{\tau} e^{2\lambda t}|y_1(t) - y_2(t)|^2 dt \leq 0. \quad (8.6)$$

Take a regular $n \times n$ -matrix $Q = Q^*$ such that

$$Q^*PQ = \begin{pmatrix} -1 & & & & \\ & -1 & & & \\ & & +1 & & \\ & & & \ddots & \\ 0 & & & & +1 \end{pmatrix} \text{ and put } y = Q \begin{pmatrix} u \\ v \end{pmatrix} \text{ with } u \in \mathbb{R}^2, v \in$$

\mathbb{R}^{n-2} ,

$\Pi y := u, \forall y \in \mathbb{R}^n$. Clearly that $|\Pi y|^2 = |u|^2$. Since $Q^{-1}y = \begin{pmatrix} u \\ v \end{pmatrix}$ we have $|Q^{-1}y|^2 = |u|^2 + |v|^2$ and $V(y) = y^*Py = (u^*, v^*)Q^*PQ \begin{pmatrix} u \\ v \end{pmatrix} = -|u|^2 + |v|^2$.

It follows that

$$\begin{aligned} V(y) + 2|\Pi y|^2 &= -|u|^2 + |v|^2 + 2|u|^2 = |u|^2 + |v|^2 \\ &= |Q^{-1}y|^2 \geq |\Pi y|^2, \quad \forall y \in \mathbb{R}^n. \end{aligned}$$

Consider two arbitrary amenable solutions y_1, y_2 of (8.6). It follows now that

$V(y_1(t) - y_2(t)) \leq 0, \forall t \geq 0$, and

$$2|\Pi(y_1(\tau) - y_2(\tau))|^2 \geq |Q^{-1}(y_1(\tau) - y_2(\tau))|^2 \geq |\Pi(y_1(\tau) - y_2(\tau))|^2. \quad (8.7)$$

If h and k are arbitrary constants the amenable solutions $y_1(t-h), y_2(t-k)$ can replace y_1, y_2 in (8.7). Thus, if γ_1, γ_2 are amenable orbits of y_1, y_2 then

$$2|\Pi p_1 - \Pi p_2|^2 \geq |Q^{-1}(p_1 - p_2)|^2 \geq |\Pi p_1 - \Pi p_2|^2 \quad \forall p_1, p_2 \in \gamma_1, \gamma_2. \quad (8.8)$$

It follows now that $\Pi : \mathcal{A} \rightarrow \Pi \mathcal{A}$ is a homeomorphism of \mathcal{A} onto $\Pi \mathcal{A}$.

■