Frequency-domain conditions for convergence to the stationary set in coupled PDEs

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1. Introduction

Suppose: Y_0 a real Hilbert space, $(\cdot, \cdot)_0$ and $\|\cdot\|_0$ the scalar product resp. the norm on Y_0 ,

 $A : \mathcal{D}(A) \to Y_0$ the generator of a C_0 -semigroup on Y_0 , $Y_1 := \mathcal{D}(A)$.

For fixed $\beta \in \rho(A) \cap \mathbb{R}$ for any $y, \eta \in Y_1$ define

$$(y,\eta)_1 := ((\beta I - A)y, (\beta I - A)\eta)_0$$
. (1)

 Y_{-1} is the completion of Y_0 with respect to the norm, $\|y\|_{-1} := \|(\beta I - A)^{-1}y\|_0$ is the scalar product

$$(y,\eta)_{-1} := \left((\beta I - A)^{-1} y, \ (\beta I - A)^{-1} \eta \right)_0, \qquad \forall \ y,\eta \in Y_{-1}.$$
(2)

 $Y_1 \subset Y_0 \subset Y_{-1}$ is a continuous embedding, i.e., for $\alpha = 1, 0$, $Y_\alpha \subset Y_{\alpha-1}, \|y\|_{\alpha-1} \leq c \|y\|_{\alpha}, \ \forall \ y \in Y_{\alpha}.$

 (Y_1, Y_0, Y_{-1}) is called a *Gelfand triple*. For any $y \in Y_0$ and $z \in Y_1$ we have

$$|(y,z)_0| = |(\beta I - A)^{-1}y, ((\beta I - A)z)_0| \le ||y||_{-1} ||z||_1.$$
 (3)

Extend $(\cdot, z)_0$ by continuity onto Y_{-1}

$$|(y,z)_0| \le ||y||_{-1} ||z||_1, \quad \forall \ y \in Y_{-1}, \forall \ z \in Y_1.$$

Denote this extension also by $(\cdot, \cdot)_{-1,1}$. Consider the Bochner measurable functions in

 $L^{2}(0,T;Y_{j}) \quad (j = 1, 0, -1)$ $\|y(\cdot)\|_{2,j} := \left(\int_{0}^{T} \|y(t)\|_{j}^{2} dt\right)^{1/2}.$ (4)

 \mathcal{L}_T is the space of functions $y \in L^2(0, T; Y_1)$, s.th. $\dot{y} \in L^2(0, T; Y_{-1})$. \mathcal{L}_T is equipped with the norm

$$\|y\|_{\mathcal{L}_{T}} := \left(\|y(\cdot)\|_{2,1}^{2} + \|\dot{y}(\cdot)\|_{2,-1}^{2}\right)^{1/2}.$$
 (5)

2. Evolutionary variational systems

Take T > 0 arbitrary and consider for a.a. $t \in [0, T]$ the evolutionary variational equation

$$(\dot{y} - Ay - B\xi - f(t), \eta - y)_{-1,1} = 0, \quad \forall \eta \in Y_1$$
 (6)
 $y(0) = y_0 \in Y_0$,

$$w(t) = Cy(t) , \quad \xi(t) = \varphi(t, w(t)) , \quad (7)$$

$$\xi(0) = \xi_0 .$$

$$z(t) = Dy(t) + E\xi(t)$$
. (8)

 $C \in \mathcal{L}(Y_{-1}, W), D \in \mathcal{L}(Y_1, Z) \text{ and } E \in \mathcal{L}(\Xi, Z),$ $\Xi, W \text{ and } Z \text{ are real Hilbert spaces, } Y_1 \subset Y_0 \subset Y_{-1} \text{ is a real}$ Gelfand triple and $A \in \mathcal{L}(Y_0, Y_{-1}), B \in \mathcal{L}(\Xi, Y_{-1}),$ $\varphi : \mathbb{R}_+ \times W \to \Xi, f : \mathbb{R}_+ \to Y_{-1}.$

Denote by $\|\cdot\|_{\Xi}$, $\|\cdot\|_W$, $\|\cdot\|_Z$ the norm in Ξ , W resp. Z.

Definition 1 Any pair of functions $\{y(\cdot), \xi(\cdot)\}$ with $y \in \mathcal{L}_T$ and $\xi \in L^2_{loc}(0, \infty; \Xi)$ such that $B\xi \in \mathcal{L}_T$, satisfying (6), (7) almost everywhere on (0, T), is called **solution of the Cauchy problem** $y(0) = y_0, \xi(0) = \xi_0$ defined for (6), (7).

Assumptions:

(C1) The Cauchy-problem (6), (7) has for arbitrary $y_0 \in Y_0$ and $\xi_0 \subset \Xi$ at least one solution $\{y(\cdot), \xi(\cdot)\}$.

(C2) The nonlinearity $\varphi : \mathbb{R}_+ \times W \to \Xi$ is a function having the property that $\mathcal{A}(t) := -A - B\varphi(t, C \cdot) : Y_1 \to Y_{-1}$ is a family of monotone hemicontinuous operators such that the inequality

 $\|\mathcal{A}(t)y\|_{-1} \leq c_1 \|y\|_1 + c_2, \quad \forall y \in Y_1,$

is satisfied, where $c_1 > 0$ and $c_2 \in \mathbb{R}$ are constants not depending on $t \in [0, T]$.

For any $y \in Y_1$ and for any bounded set $U \subset Y_1$ the family of functions $\{(\mathcal{A}(t)\eta, y)_{-1,1}, \eta \in U\}$ is equicontinuous with respect to t on any compact subinterval of \mathbb{R}_+ .

(C3) $f \in L^2_{loc}(\mathbb{R}_+; Y_{-1}).$

(C4) Consider only solutions y of (6),(7) for which \dot{y} belongs to $L^2_{loc}(\mathbb{R}; Y_{-1})$.

Definition 2 Suppose *F* and *G* are quadratic forms on $Y_1 \times \Xi$. The **class of nonlinearities** $\mathcal{N}(F,G)$ defined by *F* and *G* consists of all maps $\varphi : \mathbb{R}_+ \times W \to \Xi$ such that for any $y(\cdot) \in L^2_{loc}(0,\infty;Y_1)$ with $\dot{y}(\cdot) \in L^2_{loc}(0,\infty;Y_{-1})$ and any $\xi(\cdot) \in L^2_{loc}(0,\infty;\Xi)$ with $\xi(t) = \varphi(t,Cy(t))$ for a.e. $t \ge 0$, it follows that $F(y(t),\xi(t)) \ge 0$ for a.e. $t \ge 0$ and for any such pair $\{y,\xi\}$) there exists a continuous functional $\Phi : W \to \mathbb{R}$ such that for any times $0 \le s < t$ we have

$$\int_{s} G(y(\tau),\xi(\tau))d\tau \ge \Phi(Cy(t)) - \Phi(Cy(s)) .$$

3. Further assumptions

(F1) $A \in \mathcal{L}(Y_1, Y_{-1})$ is *regular*, i.e., for any $T > 0, y_0 \in Y_1$, $\psi_T \in Y_1$ and $f \in L^2(0, T; Y_0)$ the solutions of the direct problem

$$\dot{y} = Ay + f(t), \ y(0) = y_0, \quad \text{a.a.} \ t \in [0, T]$$

and of the dual problem

$$\dot{\psi} = -A^*\psi + f(t), \ \psi(T) = \psi_T, \quad \text{a.a. } t \in [0,T]$$

are strongly continuous in t in the norm of Y_1 . $A^* \in \mathcal{L}(Y_{-1}, Y_0)$ denotes the adjoint to A, i.e., $(Ay, \eta)_{-1,1} = (y, A^*\eta)_{-1,1}, \forall y, \eta \in Y_1.$ (F2) The pair (A, B) is L^2 -controllable, i.e., for arbitrary $y_0 \in Y_0$ exists a control $\xi(\cdot) \in L^2(0, \infty; \Xi)$ such that the problem

$$\dot{y} = Ay + B\xi, \quad y(0) = y_0$$

is well-posed on the semiaxis $[0, +\infty)$, i.e., there exists a solution $y(\cdot) \in \mathcal{L}_{\infty}$ with $y(0) = y_0$.

(F3) $F(y,\xi)$ is an Hermitian form on $Y_1 \times \Xi$, i.e.,

$$F(y,\xi) = (F_1y,y)_{-1,1} + 2\operatorname{Re}(F_2y,\xi)_{\Xi} + (F_3\xi,\xi)_{\Xi},$$

where

$$F_1 = F_1^* \in \mathcal{L}(Y_1, Y_{-1}), \ F_2 \in \mathcal{L}(Y_0, \Xi), \ F_3 = F_3^* \in \mathcal{L}(\Xi, \Xi).$$

Define the *frequency-domain condition* [Likhtarnikov and Yakubovich, 1976]

$$\alpha := \sup_{\omega, y, \xi} (\|y\|_1^2 + \|\xi\|_{\Xi}^2)^{-1} F(y, \xi) ,$$

where the supremum is taken over all triples $(\omega, y, \xi) \in \mathbb{R}_+ \times Y_1 \times \Xi$ such that $i\omega y = Ay + B\xi$.

4. Absolute observation - stability of evolutionary equations

For a function $z(\cdot) \in L^2(\mathbb{R}_+; Z)$ we denote their norm by

$$||z(\cdot)||_{2,Z} := \left(\int_0^\infty ||z(t)||_Z^2 dt\right)^{1/2}$$

Definition 3 a) The equation (6), (7) is said to be **absolutely dichotomic** (i.e., in the class $\mathcal{N}(F,G)$) with respect to the ob**servation** z from (8) if for any solution $\{y(\cdot), \xi(\cdot)\}$ of (6), (7) with $y(0) = y_0, \xi(0) = \xi_0$ the following is true: Either $y(\cdot)$ is unbounded on $[0, \infty)$ in the Y_0 -norm or $y(\cdot)$ is bounded in Y_0 in this norm and there exist constants c_1 and c_2 (which depend only on A, B and $\mathcal{N}(F, G)$ such that

$$\|Dy(\cdot) + E\xi(\cdot)\|_{2,Z}^2 \le c_1(\|y_0\|_0^2 + c_2).$$
(9)

b) The equation (6), (7) is said to be **absolutely stable with re**spect to the observation z from (8) if (9) holds for any solution $\{y(\cdot), \xi(\cdot)\}$ of (6), (7).

Definition 4 The equation (6)–(8) with $f \equiv 0$ is said to be **mini-mally stable**, i.e., there exists a bounded linear operator $K : Y_1 \rightarrow \Xi$ such that the operator A + BK is stable, i.e. for some $\varepsilon > 0$

$$\sigma(A + BK) \subset \{s \in \mathbb{C} : \operatorname{Re} s \leq -\varepsilon < 0\}$$

with
$$F(y, Ky) \geq 0, \quad \forall y \in Y_1, \qquad (10)$$

and
$$\int_{s}^{t} G(y(\tau), Ky(\tau)) d\tau \geq 0,$$

$$\forall s, t : 0 \leq s < t, \quad \forall y \in L^2_{\operatorname{loc}}(\mathbb{R}_+; Y_1). \qquad (11)$$

Theorem 1 Consider the evolution problem (6) – (8) with $\varphi \in \mathcal{N}(F,G)$. Suppose that for the operators A^c, B^c the assumptions (F1) and (F2) are satisfied. Suppose also that there exist an $\alpha > 0$ such that with the transfer operator

$$\chi^{(z)}(s) = D^{c}(sI^{c} - A^{c})^{-1}B^{c} + E^{c} \qquad (s \notin \sigma(A^{c}))$$
(12)

the frequency-domain condition

$$F^{c} ((i\omega I^{c} - A^{c})^{-1} B^{c} \xi, \xi)$$

+ $G^{c} ((i\omega I^{c} - A^{c})^{-1} B^{c} \xi, \xi) \leq -\alpha \|\chi^{(z)}(i\omega)\xi\|_{Z^{c}}^{2}$
 $\forall \omega \in \mathbb{R} : i\omega \notin \sigma(A^{c}), \quad \forall \xi \in \Xi^{c}$

is satisfied and the functional

$$J(y(\cdot),\xi(\cdot)) := \int_{0}^{\infty} \left[F^{c}(y(\tau),\xi(\tau)) + G^{c}(y(\tau),\xi(\tau)) + \alpha \|D^{c}y(\tau) + E^{c}\xi(\tau)\|_{Z^{c}}^{2}\right] d\tau$$

is bounded from above on any set

$$\mathbf{M}_{y_0} := \{ y(\cdot), \xi(\cdot) : \dot{y} = Ay + B\xi \text{ on } \mathbb{R}_+, \\ y(0) = y_0, \, y(\cdot) \in \mathcal{L}_{\infty}, \, \xi(\cdot) \in L^2(0,\infty;\Xi) \} .$$

Suppose further that the equation (6)–(8) with $f \equiv 0$ is minimally stable, i.e., (10) and (11) are satisfied with some operator $K \in \mathcal{L}(Y_1, \Xi)$ and that the pair (A + BK, D + EK) is observable in the sense of Kalman, i.e., for any solution $y(\cdot)$ of

$$\dot{y} = (A + BK)y, \quad y(0) = y_0,$$

with z(t) = (D + EK)y(t) = 0 for a.a. $t \ge 0$ it follows that $y(0) = y_0 = 0$.

Then equation (6), (7) is absolutely stable with respect to the observation z from (8).

A. L. Likhtarnikov and V.A. Yakubovich, 1976 Reitmann, V. and H. Kantz, 2003

5. Example

Consider the coupled system of Maxwell's equation and heat transfer equation

$$\begin{cases} \Psi_{tt} + \sigma(x,\theta)\Psi_t - \Psi_{xx} = 0\\ \theta_t - \theta_{xx} = \sigma(x,\theta)\Psi_t^2 \end{cases}$$
(13)

Initial-boundary conditions:

$$\Psi(0,t) = \theta(0,t) = 0,
\Psi(1,t) = \theta(1,t) = 0 \quad \forall t \in [0,T]
\Psi(x,0) = \Psi_0(x), \Psi_t(x,0) = \Psi_1(x), \theta(x,0) = \theta_0(x), \quad \forall x \in \Omega$$
(14)

Here $x \in \Omega, t \in [0, T], T > 0, \Omega = (0, 1).$

Energy inequality:

$$\sup_{0 \le t \le T} \int_0^1 [\Psi_t^2 + \Psi_x^2] dx + \int_0^T \int_0^1 \sigma(x, t, \theta) \Psi_t^2 dx dt \le C_1 + C_2 \int_0^T \int_0^1 |\theta| dx dt ,$$

where the constants C_1 and C_2 depend only on known data.

System in terms of operator equations in some function spaces:

$$y(x,t) = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \begin{pmatrix} \Psi_t(x,t) \\ \Psi(x,t) \\ \theta(x,t) \end{pmatrix}, \quad (15)$$
$$\xi(x,t) = \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = \begin{pmatrix} \sigma(x,\theta)\Psi_t(x,t) \\ \sigma(x,\theta)\Psi_t^2(x,t) \end{pmatrix}.$$

Let us define operators A, B from equation (6). Let Λ be the selfadjoint positiv operator, generated on $L^2(0, 1)$ by the differential expression $\Lambda(v) = -v_{xx}$ and zero boundary conditions (14). Consider the following spaces $Y_0 = L^2(0, 1) \times L^2(0, 1) \times L^2(0, 1)$, $Y_1 = W^{1,2}(0, 1) \times W^{1,2}(0, 1) \times W^{1,2}(0, 1)$ and $\Xi = L^2(0, 1) \times L^2(0, 1)$ as defined in Section 1. Thus (**F1**) of Theorem 1 is satisfied.

Then operators A and B are defined as follows:

$$A = \begin{bmatrix} -\sigma_0 I & \Lambda & 0 \\ -I & 0 & 0 \\ 0 & 0 & -\Lambda \end{bmatrix}, B = \begin{bmatrix} -I & 0 \\ 0 & 0 \\ 0 & I \end{bmatrix}, \quad (16)$$

Here constant $\sigma_0 > 0$ is derived from decomposition $\sigma(x, \theta) = \sigma_0 + \overline{\sigma}(x, \theta)$.

Finally, system (13) can be written in terms of the operator equation

$$\frac{dy}{dt} = Ay + B\xi \tag{17}$$

Consider the quadratic form $F(y,\xi)$ defined by

$$F(y,\xi) = y_1 \cdot \xi_1 = \Psi_t(x,t) \cdot \sigma(x,\theta) \Psi_t(x,t).$$
(18)

The pair (A, B) is L^2 – controllable since the matrix operator A is stable.

Consider the eigenvalue equation for A

$$Av = \lambda v. \tag{19}$$

Denote by λ_i the eigenvalues of operator Λ and by e_k its eigenvectors, such that $\{e_k\}_k$ forms a basis of $L^2(0, 1)$.

Vector v can be decomposed in this basis $\{e_k\}_k$ as

$$v_i = \sum_k c_i^k e_k \, .$$

Eigenvalue equation (19):

$$\begin{cases} -\upsilon_1 = \lambda \upsilon_2 \\ -\sigma_0 \upsilon_1 + A_0 \upsilon_2 = \lambda \upsilon_1 \\ -A_0 \upsilon_3 = \lambda \upsilon_3 \end{cases}$$

$$\begin{cases} -\sum_{k} c_{1}^{k} e_{k} = \lambda \sum_{k} c_{2}^{k} e_{k} \\ -\sigma_{0} \sum_{k} c_{1}^{k} e_{k} + \sum_{k} \lambda_{k} c_{2}^{k} e_{k} = \lambda \sum_{k} c_{1}^{k} e_{k} \\ -\sum_{k} \lambda_{k} c_{3}^{k} e_{k} = \lambda \sum_{k} c_{3}^{k} e_{k} \end{cases}$$
(20)

Verification of the frequency domain condition:

Functions $\Psi(x,t)$, $\theta(x,t)$, $\xi(x,t)$ can be decomposed by $\{e_k\}_k$ as follows:

$$\Psi(x,t) = \sum_{k} \Psi^{k}(t)e_{k}, \quad \theta(x,t) = \sum_{k} \theta^{k}(t)e_{k},$$
$$\xi(x,t) = \sum_{k} \xi^{k}(t)e_{k}.$$

Introduce the quadratic form $(\Pi_0(i\omega)\xi,\xi) = \tilde{F}(y,\xi)$, where $\tilde{F}(y,\xi)$ is the extension of the quadratic form $F(y,\xi)$ to the Hermitian form (F3).

Then the matrix-function $\Pi_0(i\omega)$ can be presented as

$$(\Pi_0(i\omega)\tilde{\xi},\tilde{\xi}) = \sum_k (\Pi_0^k(i\omega)\tilde{\xi}^k,\tilde{\xi}^k).$$
(21)

Fourier transform with respect to *t*:

$$-\omega^{2}\widetilde{\Psi^{k}}(i\omega) + i\omega\sigma_{0}\widetilde{\Psi^{k}}(i\omega) - \lambda_{k}\widetilde{\Psi^{k}}(i\omega) + \widetilde{\xi_{1}^{k}}(i\omega) = 0$$

$$i\omega\widetilde{\theta^{k}}(i\omega) + \lambda_{k}\widetilde{\theta^{k}}(i\omega) - \widetilde{\xi_{2}^{k}}(i\omega) = 0$$
(22)

From (22) $\widetilde{\Psi^k}$ and $\widetilde{\theta^k}$ can be expressed in terms of $\widetilde{\xi_1^k}, \widetilde{\xi_2^k}$ in the following way:

$$\widetilde{\Psi^{k}}(i\omega) = \chi_{0}(i\omega,\lambda_{k})\xi_{1}^{k}(i\omega),$$

$$\widetilde{\theta^{k}}(i\omega) = \chi_{1}(i\omega,\lambda_{k})\xi_{2}^{k}(i\omega),$$

where

$$\chi_0(i\omega,\lambda_k) = (\omega^2 - i\omega\sigma_0 + \lambda_k)^{-1}, \chi_1(i\omega,\lambda_k) = (i\omega + \lambda_k)^{-1}.$$

 $(\Pi_0^k(i\omega)\widetilde{\xi^k},\widetilde{\xi^k})$ from (21) can be written as follows:

$$(\Pi_0^k(i\omega)\widetilde{\xi^k},\overline{\widetilde{\xi^k}})) = \operatorname{Re}\widetilde{\Psi_t^k} \,\overline{\widetilde{\xi_1^k}} = \operatorname{Re}(i\omega\chi_0)|\widetilde{\xi_1^k}(i\omega)|^2$$

Here the matrix $\Pi_0^k(i\omega)$ has the following form

$$\Pi_0^k(i\omega) = \begin{pmatrix} \operatorname{Re}(i\omega\chi_0) & 0\\ 0 & 0 \end{pmatrix}$$
(23)

We have to check that

$$\operatorname{Re}(i\omega\chi_0) < 0, \forall \omega \in \mathbb{R}, \omega \neq 0$$
Condition (24) is equivalent to
$$\operatorname{Re}(\frac{i\omega}{\omega^2 - i\omega\sigma_0 + \lambda_k}) < 0.$$
(24)

This is satisfied if $-\omega^2 \sigma_0 < 0, \forall \omega \neq 0$.

Remark We can also consider another quadratic form instead of (18)

$$F(y,\xi) = -y_3\xi_2 + ay_1\xi_1 + b\xi_1^2$$
(25)

For the slightly modified version of equation (13):

$$\begin{cases} \Psi_{tt} + \sigma(x,\theta)\Psi_t - \Psi_{xx} = 0\\ \theta_t - \theta_{xx} = \sigma(x,\theta)\Psi_t^2 + \varepsilon\Psi \end{cases}$$
(26)

6. Experimental results

Consider system (13) - (14) in the form

$$\begin{cases} h_t + \sigma(x,\theta)h - \Psi_{xx} = 0\\ \Psi_t = h\\ \theta_t - \theta_{xx} = \sigma(x,\theta)h^2 \end{cases}$$
(27)

Initial-boundary conditions:

$$\Psi(0,t) = \theta(0,t) = 0, \Psi(1,t) = \theta(1,t) = 0 \quad \forall t \in [0,T] \Psi(x,0) = \Psi_0(x), h(x,0) = h_0(x), \theta(x,0) = \theta_0(x), \forall x \in \Omega$$
(28)

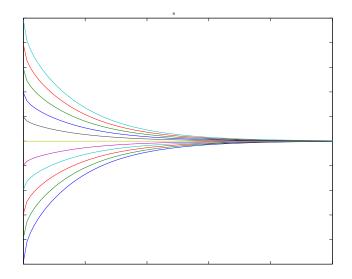
 $h_0(x) = p \cdot (1 - |2x - 1|), \Psi_0(x) \equiv 0, \theta_0(x) = p \cdot (1 - |2x - 1|),$ where $p \in \mathbb{R}$ is some parameter.

J. Morgan, H.-M. Yin, 2001

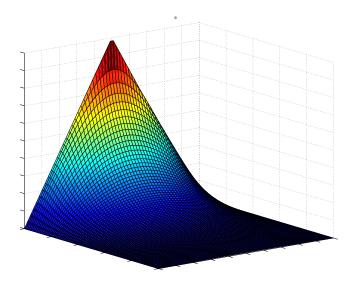
Electrical conductivity: $\sigma(x,\theta) = c + \theta(x,t)$, where c is some positive constant.

For convention: Denote h(x, t) by $\Psi_t(x, t)$.

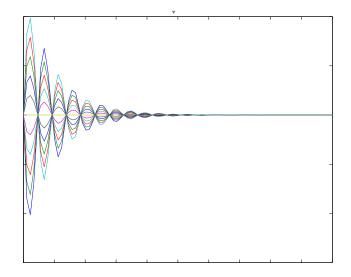
Consider solutions $(\Psi_t^p(x,t), \Psi^p(x,t), \theta^p(x,t))$ with $p \in [-0.5, 0.5]$.



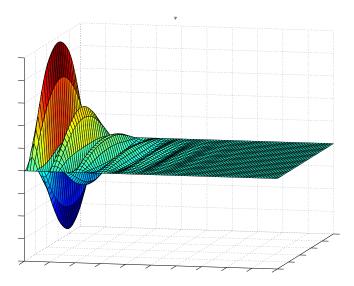
 $\theta^p(x_0, t), x_0 = 0.5, t \in (0, 0.25)$



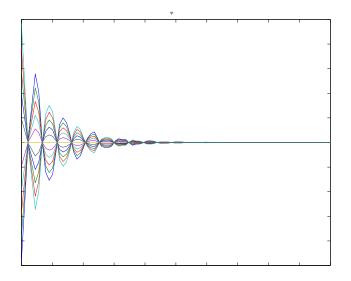
 $\theta^p(x,t), t \in (0, 0.25), p = 0.5$



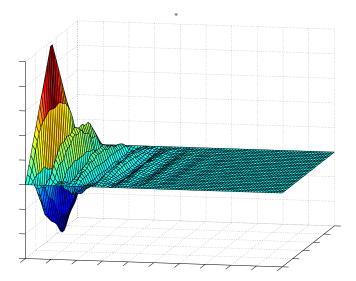
$$\Psi^p(x_0,t), x_0 = 0.5, t \in (0,200)$$



 $\Psi^p(x,t), t \in (0, 200), p = 0.5$



 $\Psi_t^p(x_0,t), x_0 = 0.5, t \in (0,200)$



 $\Psi_t^p(x,t), t \in (0, 200), p = 0.5$

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