

Determining functionals for bifurcations on a finite-time interval in variational inequalities

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1. Evolutionary variational inequalities

Suppose that Z_0 is a real Hilbert space with $(\cdot, \cdot)_0$ and $\|\cdot\|_0$ as scalar product resp. norm. Suppose also that $A : \mathcal{D}(A) \subset Z_0 \rightarrow Z_0$ is an unbounded densely defined linear operator. The Hilbert space Z_1 is defined as $\mathcal{D}(A)$ equipped with the scalar product

$$(z, \eta)_1 := ((\beta I - A)z, (\beta I - A)\eta)_0, \quad z, \eta \in \mathcal{D}(A), \quad (1)$$

where $\beta \in \rho(A) \cap \mathbb{R}$ ($\rho(A)$ the resolvent set of A) is an arbitrary but fixed number the existence of which we assume.

The Hilbert space Z_{-1} is by definition the completion of Z_0 with respect to the norm $\|z\|_{-1} := \|(\beta I - A)^{-1}z\|_0$. Thus we have the dense and continuous imbedding

$$Z_1 \subset Z_0 \subset Z_{-1} \quad (2)$$

which is called *Hilbert space rigging structure* (Yu. M. Berezanskii, 1965). The *duality pairing* $(\cdot, \cdot)_{-1,1}$ on $Z_{-1} \times Z_1$ is the unique extension by continuity of the functionals $(\cdot, z)_0$ with $z \in Z_1$ onto Z_{-1} . If $T > 0$ is an arbitrary number we define the norm for Bochner measurable functions in $L^2(0, T; Z_j)$, $j = 1, 0, -1$ through

$$\|z\|_{2,j} := \left(\int_0^T \|z(t)\|_j^2 dt \right)^{1/2}. \quad (3)$$

Let \mathcal{W}_T be the space of functions $z(\cdot) \in L^2(0, T; Z_1)$ for which $\dot{z}(\cdot) \in L^2(0, T; Z_{-1})$, equipped with the norm

$$\|z(\cdot)\|_{\mathcal{W}_T} := \left(\|z(\cdot)\|_{2,1}^2 + \|\dot{z}(\cdot)\|_{2,-1}^2 \right)^{1/2}. \quad (4)$$

Assume that U and W are two other real Hilbert spaces with scalar products $(\cdot, \cdot)_U$, $(\cdot, \cdot)_W$ and norms $\|\cdot\|_U$, $\|\cdot\|_W$, respectively.

Introduce the linear continuous operators

$$A : Z_1 \rightarrow Z_{-1}, \quad B : U \rightarrow Z_{-1}, \quad C : Z_1 \rightarrow W, \quad (5)$$

(A from above) and define the set-valued map

$$\varphi : \mathbb{R}_+ \times W \rightarrow 2^U \quad (6)$$

and the map

$$\psi : Z_1 \rightarrow \mathbb{R}_+ . \quad (7)$$

Consider the *evolutionary variational inequality* with set-valued non-linearity

$$(\dot{z} - Az - Bu, \eta - z)_{-1,1} + \psi(\eta) - \psi(z) \geq 0, \quad \forall \eta \in Z_1, \quad (8)$$

$$w(t) = Cz(t), \quad u(t) \in \varphi(t, w(t)), \quad y(0) = y_0 \in Z_0. \quad (9)$$

G. Duvant and J.-L. Lions (1976), W. Han and M. Sofonea (2000), K.L. Kuttler and M. Shillor (1999)

Definition 1.1 A function $z(\cdot) \in \mathcal{W}_T \cap C(0, T; Z_0)$ is said to be a solution of (8), (9) on $(0, T)$ if there exists a function $u(\cdot) \in L^2(0, T; U)$ such that for a.a. $t \in (0, T)$ the inequality (8), (9) is satisfied and $\int_0^T \psi(z(t)) dt < +\infty$. The pair $\{z(\cdot), u(\cdot)\}$ is called a response of (8), (9); $u(\cdot)$ is an associated selection.

Suppose that \mathcal{F} and \mathcal{G} are two quadratic forms on $Z_1 \times U$. The class $\mathcal{N}(\mathcal{F}, \mathcal{G})$ of nonlinearities for (8), (9) consists of all maps (6) such that the following condition is satisfied:

For any $T > 0$ and any two functions $z(\cdot) \in L^2(0, T; Z_1)$ and $u(\cdot) \in L^2(0, T; U)$ with

$$u(t) \in \varphi(t, Cz(t)) \quad \text{for a.a. } t \in [0, T], \quad (10)$$

it follows that

$$\mathcal{F}(z(t), u(t)) \geq 0 \quad \text{for a.a. } t \in [0, T], \quad (11)$$

and there exists a continuous function $\Phi : Z_1 \rightarrow \mathbb{R}_+$ s. t.

$$\int_s^t \mathcal{G}(z(\tau), u(\tau)) d\tau \geq \Phi(z(t)) - \Phi(z(s)) \geq -\Phi(z(s)) \quad (12)$$

for all $0 \leq s < t \leq T$.

2. Frequency-domain conditions for finite-time stability

Suppose that $0 \leq t_0 < T_0$, $T > 0$ with $t_0 + T < T_0$, and $0 < \alpha < \beta$ are arbitrary numbers.

Definition 2.1 *The inequality (8), (9), Sect. 1, is called (α, β, t_0, T) -stable if for any solution $z(\cdot)$ from $\|z(t_0)\|_0 < \alpha$ it follows that $\|z(t)\|_0 < \beta$ for all $t \in [t_0, t_0 + T)$.*

Theorem 2.1 *The inequality (8), (9), Sect. 1, is (α, β, t_0, T) -stable if there exist a continuous functional V on $Z_0 \times [t_0, t_0 + T)$ and an integrable on $J := [t_0, t_0 + T)$ real-valued function g such that the following conditions are satisfied:*

$$(i) \quad V(z(t), t) - V(z(s), s) < \int_s^t g(\tau) d\tau \quad (1)$$

for all $s, t \in J, s < t$, and all functions $z(\cdot) \in \mathcal{W}(J, Z_0) \cap C(J, Z_0)$ such that

$$\alpha \leq \|z(t)\|_0 \leq \beta \text{ for all } t \in J;$$

$$(ii) \quad \int_s^t g(\tau) d\tau \leq \min_{z \in Z_0: \|z\|_0 = \beta} V(z, t) - \max_{z \in Z_0: \|z\|_0 = \alpha} V(z, s) \quad (2)$$

for all $s, t \in J, s < t$.

ODE-case: L. Weiss and E.F. Infante (1965), A.N. Michel and D.W. Porter (1972)

The pair of operators (A, B) from (8), (9), Sect. 1, is *stabilizable*, if there exists an operator $S \in \mathcal{L}(Z_0, U)$ such that any solution $z(\cdot)$ of the Cauchy-problem $\dot{z} = (A + BS)z, z(0) = z_0$, decreases exponentially as $t \rightarrow +\infty$, i.e.,

$$\exists c > 0 \exists \varepsilon > 0 : \|z(t)\|_0 \leq c e^{-\varepsilon t} \|z_0\|_0, \quad \forall t \geq 0.$$

The complexification of a real Hilbert space $(H, (\cdot, \cdot)_H)$ and a real linear operator L are denoted by $(H^c, (\cdot, \cdot)_{H^c})$ and L^c , respectively. For a real quadratic form \mathcal{F} we denote their Hermitian extension by \mathcal{F}^c . We introduce for the pair (A, B) from (8), (9), Sect. 1, the frequency-domain characteristic

$$\chi(i\omega) = (i\omega I^c - A^c)^{-1} B^c. \quad (3)$$

Let us also introduce the real Hilbert space Y with scalar product $(\cdot, \cdot)_Y$ and norm $\|\cdot\|_Y$.

For this we define the linear operators $M \in \mathcal{L}(Z_1, Y)$ and $N \in \mathcal{L}(U, Y)$ s.t. for any response $\{z(\cdot), u(\cdot)\}$ of (8), (9), Sect. 1,

$$y(t) := Mz(t) + Nu(t) \in Y, \quad t \in [0, T_0]. \quad (4)$$

Lemma 2.1 *Suppose that the pair (A, B) is stabilizable, $\varphi \in \mathcal{N}(\mathcal{F}, \mathcal{G})$, and there exist numbers $\varepsilon > 0$ and $\delta \in \mathbb{R}$ such that*

$$\begin{aligned} \mathcal{F}^c(\chi(i\omega)u, u) + \mathcal{G}^c(\chi(i\omega)u, u) + \delta \| [M^c \chi(i\omega) + N^c] u \|_{Y^c}^2 \\ + \varepsilon [\|\chi(i\omega)u\|_{Z_1^c}^2 + \|u\|_{U^c}^2] \leq 0, \end{aligned} \quad (5)$$

for all $\omega \in \mathbb{R}$ with $i\omega \notin \sigma(A^c)$ and all $u \in U^c$. Then there exists a real operator

$P = P^* \in \mathcal{L}(Z_0, Z_0)$ such that for any response $\{z(\cdot), u(\cdot)\} \neq \{0, 0\}$ of (8), (9), Sect. 1, and for any s, t with $0 < s \leq t < T_0$ we have

$$\begin{aligned} (z(t), Pz(t))_0 - (z(s), Pz(s))_0 < \\ \int_s^t [\psi(-Pz(\tau) + z(\tau)) - \psi(z(\tau)) + \\ \delta \| Mz(\tau) + Nu(\tau) \|_Y^2] d\tau + \Phi(z(s)). \end{aligned} \quad (6)$$

A.L. Likhtarnikov and V.A. Yakubovich (1976)

V.A. Brusin (1976)

L. Pandolfi (1998)

Corollary 2.1 Suppose that there exist operators

$P = P^* \in \mathcal{L}(Z_0, Z_0)$, $M \in \mathcal{L}(Z_1, Y)$, $N \in \mathcal{L}(U, Y)$ and a number $\delta \in \mathbb{R}$ such that the inequality (6) is satisfied. Assume that $0 < \alpha < \beta$ and $T > 0$ with $t_0 + T < T_0$ are arbitrary numbers. Then for any response $\{z(\cdot), u(\cdot)\}$ of (8), (9), Sect. 1, with $\alpha \leq \|z(t)\|_0 \leq \beta$ for $t \in [t_0, t_0 + T)$ and any s, t with $0 < s \leq t \leq t_0 + T$ the inequality

$$V(z(t)) - V(z(s)) < \int_s^t g(\tau) d\tau \quad (7)$$

is satisfied.

Here

$$V(z) := (z, Pz)_0, \quad z \in Z_0, \quad \text{and} \quad (8)$$

$$g(t) := \sup[\psi(-Pz(t) + z(t)) - \psi(z(t)) + \delta \|Mz(t) + Nu(t)\|_Y^2 + \frac{1}{T} \Phi(z(0))], \quad (9)$$

where the supremum is taken over all pairs $\{z(\cdot), u(\cdot)\}$ with $z(\cdot) \in L^2(t_0, t_0 + T; Z_0)$, $u(\cdot) \in L^2(t_0, t_0 + T; U)$ such that $\alpha \leq \|z(t)\|_0 \leq \beta$, $\mathcal{F}(z(t), u(t)) \geq 0$ and $\mathcal{G}(z(t), u(t)) \geq -\Phi(z(t))$ for a.a. $t \in [t_0, t_0 + T)$.

Theorem 2.2 Suppose that the assumptions of Lemma 3.1 are satisfied and, with the operators P, M, N and the number δ from this lemma, the inequality (6) holds. If with the functions V and g from (8), (9) and arbitrary s, t with $t_0 \leq s \leq t \leq t_0 + T$ the inequality

$$\int_s^t g(\tau) d\tau \leq \min_{z \in Z_0: \|z\|_0 = \beta} V(z) - \max_{z \in Z_0: \|z\|_0 = \alpha} V(z) \quad (10)$$

is satisfied, then the variational inequality (8), (9), Sect. 1, is (α, β, t_0, T) -stable.

3. Determining observation functionals via the algebra of operator-symbols

Recall that $H^\infty(G)$ is a subspace of $L^2(\mathbb{R}^m)$ consisting of all such (complex valued) functions the Fourier transform of which is compactly supported in G .

Yu.A. Dubinskii (1982)

Consider the Cauchy problem for the variational equation

$$\frac{\partial z}{\partial t} = A(D)z + B(D)u(x, t), \quad z(x, 0) = z_0(x), \quad (1)$$

$$w(x, t) = C(D)z(x, t), \quad u(x, t) \in \varphi(t, w(x, t)), \quad (2)$$

where $A(D), B(D)$ and $C(D)$ are Ψ DO's with constant coefficients the symbols of which are real analytic in G . The action of these linear operators is supposed as

$$A(D) : [H^\infty(G)]^n \rightarrow [H^{-\infty}(G)]^n, \quad (3)$$

$$B(D) : [H^\infty(G)]^k \rightarrow [H^{-\infty}(G)]^n, \quad (4)$$

$$C(D) : [H^\infty(G)]^n \rightarrow [H^\infty(G)]^l, \quad (5)$$

where n, k and l are natural numbers.

We assume the representation

$$A(D) = \sum_{|\alpha|=0}^{\infty} A_\alpha D^\alpha, \quad B(D) = \sum_{|\alpha|=0}^{\infty} B_\alpha D^\alpha,$$

$$C(D) = \sum_{|\alpha|=0}^{\infty} C_\alpha D^\alpha \quad (6)$$

where $\alpha = (\alpha_1, \dots, \alpha_m)$ are multiindices, $D = (D_1, \dots, D_m)$ with $D_j = \frac{1}{i} \frac{\partial}{\partial x_j}$ ($j = 1, \dots, m$) are again the elementary differential operators and A_α, B_α and C_α are constant $n \times n$ -, $n \times k$ - and $l \times n$ -matrices, respectively. The associated symbols

$$A(\xi) = \sum_{|\alpha|=0}^{\infty} A_\alpha \xi^\alpha, \quad B(\xi) = \sum_{|\alpha|=0}^{\infty} B_\alpha \xi^\alpha, \quad C(\xi) = \sum_{|\alpha|=0}^{\infty} C_\alpha \xi^\alpha \quad (7)$$

are real analytic in G matrix-valued functions. The nonlinear part of (1), (2) is given as set-valued map

$$\varphi : \mathbb{R}_+ \times [H^\infty(G)]^l \rightarrow 2^{[H^\infty(G)]^k}. \quad (8)$$

The initial function is assumed as $z_0 \in [H^\infty(G)]^n$. The equation (1), (2), (8) is understood in the sense of distributions.

The class of nonlinearities (8) is described by an Hermitian form \mathcal{F} on $[H^\infty(G)]^n \times [H^\infty(G)]^k$ given by

$$\mathcal{F}(z, u) = (F_1(D)z, z)_{-\infty, \infty} + 2 \operatorname{Re} (F_2(D)u, z)_{-\infty, \infty} + (F_3(D)u, u) \quad (9)$$

where

$$\left. \begin{aligned} F_1(D) &= F_1^*(D) \in \mathcal{L}([H^\infty(G)]^n, [H^{-\infty}(G)]^n), \\ F_2(D) &\in \mathcal{L}([H^\infty(G)]^k, [H^{-\infty}(G)]^n), \\ F_3(D) &= F_3^*(D) \in \mathcal{L}([H^\infty(G)]^k, [H^\infty(G)]^k) \end{aligned} \right\} \quad (10)$$

are Ψ DO's with constant coefficients, the symbols

$$F_i(\xi) = \sum_{|\alpha|=0}^{\infty} F_{i\alpha} \xi^\alpha, \quad i = 1, 2, 3,$$

of which are real analytic in G .

M. Taylor (1981), F. Trèves (1980)

The finite-time stability problem can be reduced to the problem of solving the Lur'e operator equations

$$\left. \begin{aligned} A^*(D)P(D) + P(D)A(D) + L(D)L^*(D) &= -F_1(D), \\ P(D)B(D) - L(D)K(D) &= -F_2(D), \\ K(D)K^*(D) &= -F_3(D), \end{aligned} \right\} \quad (11)$$

where $P(D) = P^*(D) \in \mathcal{L}([H^{\pm\infty}(G)]^n, [H^{\pm\infty}(G)]^n)$,
 $L(D) \in \mathcal{L}([H^\infty(G)]^k, [H^{-\infty}(G)]^n)$, and
 $K(D) = K^*(D) \in \mathcal{L}([H^\infty(G)]^k, [H^\infty(G)]^k)$

are unknown Ψ DO's with constant coefficients the symbols of which are real analytic in G .

In order to solve (11) we use, as it was done in, the isomorphism between the algebra of Ψ DO's with constant coefficients and analytic symbols and the algebra of analytic matrix-valued functions which describe the symbols. This means that we have to solve the matrix-valued Lur'e problem

$$\left. \begin{aligned} A^*(\xi)P(\xi) + P(\xi)A(\xi) + L(\xi)L^*(\xi) &= -F_1(\xi), \\ P(\xi)B(\xi) - L(\xi)K(\xi) &= -F_2(\xi), \\ K(\xi)K^*(\xi) &= -F_3(\xi), \end{aligned} \right\} \quad (12)$$

where the given real analytic in G matrix-valued functions $A(\xi)$, $B(\xi)$, $F_1(\xi)$, $F_2(\xi)$ and $F_3(\xi)$ are of order $n \times n$, $n \times k$, $n \times n$, $n \times k$ and $k \times k$, respectively, and the unknown real analytic in G matrix-valued functions $P(\xi) = P^*(\xi)$, $L(\xi)$ and $K(\xi) = K^*(\xi)$ are of order $n \times n$, $n \times k$ and $k \times k$, respectively.

A.L. Likhtarnikov (1989)

Remark 3.1 Suppose that the Ψ DO's A, B, C, F_1, F_2 and F_3 in (12) depend continuously on the time $t \in \mathbb{R}$. Then the calculation of a time-dependent quadratic measurement functional V in the

sense of Theorem 1.1, which is represented by a pseudo differential operator $P(t, D)$ in $H^\infty(G)$ can be reduced to the problem of solving *differential Lur'e-Riccati equations* for absolute continuous in t and real analytic in ξ symbols $P(t, \xi)$, $L(t, \xi)$ and $K(t, \xi)$ in $\mathbb{R} \times G$:

$$\left. \begin{aligned} \dot{P}(t, \xi) + A^*(t, \xi)P(t, \xi) + P(t, \xi)A(t, \xi) + L(t, \xi)L^*(t, \xi) &= -F_1(t, \xi) , \\ P(t, \xi)B(t, \xi) - L(t, \xi)K(t, \xi) &= -F_2(t, \xi) , \\ K(t, \xi)K^*(t, \xi) &= -F_3(t, \xi) . \end{aligned} \right\} \quad (13)$$

Sufficient frequency-domain conditions for the solvability of (13) are given in V.A. Yakubovich, 1986 (periodic in t case) and in A.V. Savkin, 1993 (general bounded in t case).

Example 3.1 Consider the heat equation on an infinite bar

$$\frac{\partial z}{\partial t} = a \frac{\partial^2 z}{\partial x^2} + u(x, t) , \quad (14)$$

$$u(x, t) = \varphi(z(x, t)) , \quad z(x, 0) = z_0(x) , \quad (15)$$

where $a > 0$ is a parameter and $\varphi : \mathbb{R} \rightarrow \mathbb{R}$ is a given nonlinear function which satisfies the inequality

$$\|\varphi(z)\| \leq \mu \|z\| , \quad \forall z \in L^2(\mathbb{R}) . \quad (16)$$

Here $\|\cdot\|$ denotes the norm in $L^2(\mathbb{R})$ and $0 < \mu < 2$ is also a parameter. It follows that φ is characterized by the quadratic form in $L^2(\mathbb{R}) \times L^2(\mathbb{R})$ given as

$$\mathcal{F}(z, u) := \mu^2 \|z\|^2 - \|u\|^2 . \quad (17)$$

$$A(\xi) = -a \xi^2 , \quad B(\xi) \equiv 1 , \quad (18)$$

$$F_1(\xi) \equiv \mu^2 , \quad F_2(\xi) \equiv 0 , \quad F_3(\xi) \equiv -1 . \quad (19)$$

$$\chi(i\omega, \xi) = (i\omega + a\xi^2)^{-1}. \quad (20)$$

$$G'_1 := \{(\xi, \omega) \in \mathbb{R}^2 : (1 - a\xi^2)^2 + \omega^2 < 1\}. \quad (21)$$

$$\mathcal{F}(\chi(i\omega, \xi)u, u, \xi) =: u^* \Pi(i\omega, \xi)u.$$

$$\Pi(i\omega, \xi) = \mu^2 |\chi(i\omega, \xi)|^2 - 1. \quad (22)$$

$$G' := \{(\omega, \xi) \in \mathbb{R}^2 : \xi > 0, \mu^2 < \omega^2 + a^2\xi^4 < 2a\xi^2\}.$$

$$\begin{aligned} G &:= \text{proj } G' = \{\xi > 0 : \mu^2 < a^2\xi^4 < 2a\xi^2\} \\ &= \left\{ \xi \in \mathbb{R} : \sqrt{\mu/a} < \xi < \sqrt{2/a} \right\}. \end{aligned}$$

The pair $(A(\xi), B(\xi))$ from (18) is stabilizable in G .

Lur'e equations in G :

$$-2P(\xi)a\xi^2 + L^2(\xi) = -\mu^2, \quad (23)$$

$$P(\xi) - L(\xi)K(\xi) = 0, \quad (24)$$

$$K^2(\xi) = 1. \quad (25)$$

$$\implies K(\xi) \equiv 1, P(\xi) \equiv L(\xi).$$

Equation for $P(\cdot)$ in G :

$$P^2(\xi) - 2a\xi^2P(\xi) + \mu^2 = 0, \quad (26)$$

$$P(\xi) = a\xi^2 + \sqrt{a^2\xi^4 - \mu^2}.$$